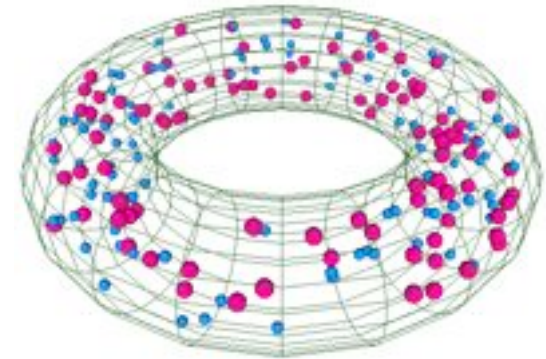


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## Global Kinetic MHD Simulation by the Gyrokinetic PIC Code



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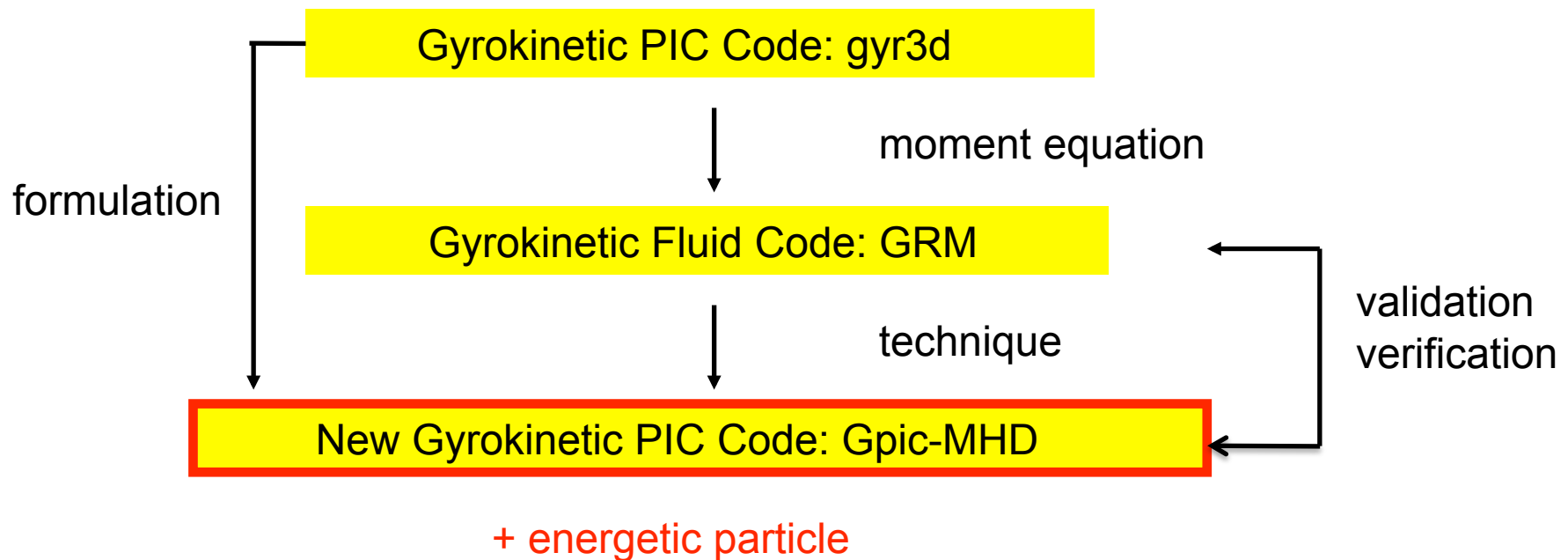
Research Institute for Applied Mechanics, Kyusyu University

# Outline

1. Motivation
2. Gyro-Reduced-MHD code
3. Gpic-MHD code
4. Simulation results of collisionless (kinetic) internal kink mode
5. Performance on the parallel computer
6. Revisit the formulation of Split-weight scheme
7. Summary

# 1. Motivation

The simulation model, which can treat the **kinetic MHD** or **extended MHD** phenomena, is necessary to study the MHD-like phenomena in the present day and future high temperature large tokamaks.



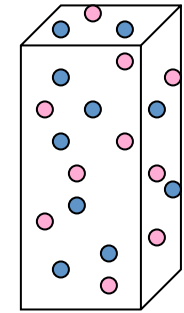
# simulation of collisionless (kinetic) internal kink mode

## Gyrokinetic Particle Simulation

H. Naitou, K. Tsuda, W.W. Lee, R.D. Sydora,  
Phys. Plasmas 2, 4257 (1995)

$$L_x \times L_y \times L_z = 16 d_e \times 16 d_e \times 8000 d_e$$
$$d_e / a = 0.125, \quad \rho_s / a = 0.03125 \quad \Rightarrow \quad v_{te} / v_A = 0.25$$

low  $\beta$



## Gyrokinetic Fluid Simulation

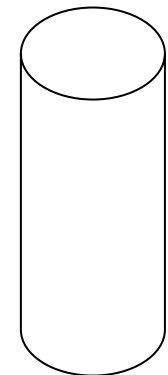
## Gyro-Reduced-MHD (GRM) simulation

$$d_e / a \approx 0.001, \quad \rho_s / a \approx 0.003 \quad \Rightarrow \quad v_{te} / v_A \approx 3$$

low  $\beta$

+

high  $\beta$



## 2. Gyro-Reduced-MHD Code

### 3-field model

- vortex equation
- ohm's law along the magnetic field including **electron inertia** and **pressure** terms
- electron conservation law  
isothermal model  
 $T_i = 0, \quad \Gamma_i = 0$  (ion velocity parallel to B)

### 5-field model

- 3-field model +
- equation for  $\Gamma_i$
- equation for  $T_i$  (perturbed temp.)  
**Linear Ion Landau damping** term is added to the equation for the perturbed ion temperature.

$$T_{i\perp} = 0$$

$$T_{i//}^0 = \text{const}$$

# Model Including Ion Landau Damping

$$\frac{\partial}{\partial t} \nabla_{\perp}^2 \phi = -\frac{\mathbf{b} \times \nabla \phi \cdot \nabla (\nabla_{\perp}^2 \phi)}{B_0} - v_A^2 \mathbf{b}^* \cdot \nabla (\nabla_{\perp}^2 A_z)$$

$$\frac{\partial}{\partial t} A_z = -\mathbf{b}^* \cdot \nabla \phi + d_e^2 \frac{d}{dt} (\nabla_{\perp}^2 A_z) + \frac{T_{e0}}{n_{e0} e} \mathbf{b}^* \cdot \nabla n_e$$

$$\frac{\partial}{\partial t} n_e = -\frac{\mathbf{b} \times \nabla \phi \cdot \nabla n_e}{B_0} - \frac{1}{e \mu_0} \mathbf{b}^* \cdot \nabla (\nabla_{\perp}^2 A_z) - \mathbf{b}^* \cdot \nabla \Gamma_i$$

3-Field  
Model

$$\Gamma_i = 0$$

$$\frac{\partial}{\partial t} \Gamma_i = -\frac{\mathbf{b} \times \nabla \phi \cdot \nabla \Gamma_i}{B_0} - \left( \frac{T_{e0}}{m_i} + \frac{T_{i0}}{m_i} \right) \mathbf{b}^* \cdot \nabla n_e$$

$$+ \frac{\epsilon_0 T_{i0} \omega_{pi}^2}{m_i \omega_{ci}^2} \mathbf{b}^* \cdot \nabla (\nabla_{\perp}^2 \phi) - \frac{n_{i0}}{m_i} \mathbf{b}^* \cdot \nabla \tilde{T}_i$$

added

$$\frac{\partial}{\partial t} \tilde{T}_i = -\frac{\mathbf{b} \times \nabla \phi \cdot \nabla \tilde{T}_i}{B_0} - T_{i0} \mathbf{b}^* \cdot \nabla V_i - \frac{2^{3/2}}{\sqrt{\pi}} |k_{11}| v_{Ti} \tilde{T}_i$$

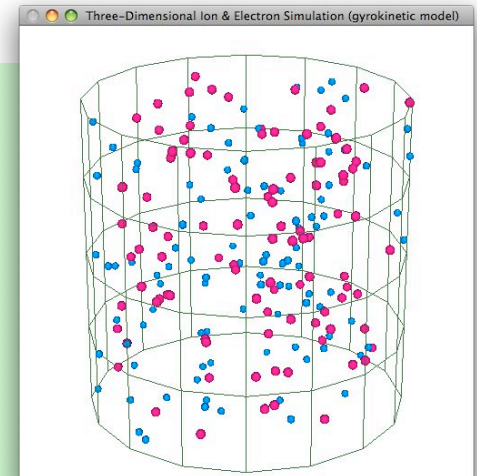
$\tilde{T}_i$  : perturbed ion temperature

ion Landau damping

# 3. Gpic-MHD code

## Gyrokinetic PIC code for MHD simulation

- Cylindrical geometry.
- Same normalization as the GRM-code.
- Helical Symmetry is assumed.
- Limit of  $k_{\perp}\rho_i \ll 1$
- Benchmark with the results of the GRM-code.
- Utilize techniques developed for the fluid code.
  - mesh accumulation, mode selection, etc.
- \*\*\*\*\*
- To include new algorithm
  - split weight method, etc.



## 4. Simulation results of kinetic internal kink mode

Cylindrical geometry

Single-helicity version

Nonuniform mesh in the radial direction

Single helicity (2D - code)

Gyrokinetic PIC code with  $\delta f$  scheme

Parallelization by particle decomposition

Benchmark run :

$$d_e / a = 0.06, \quad \rho_s / a = 0.06, \quad T_i / T_e = 1.0$$

$$N_r = 129, \quad N_\theta = 128$$

$$m \leq 20$$

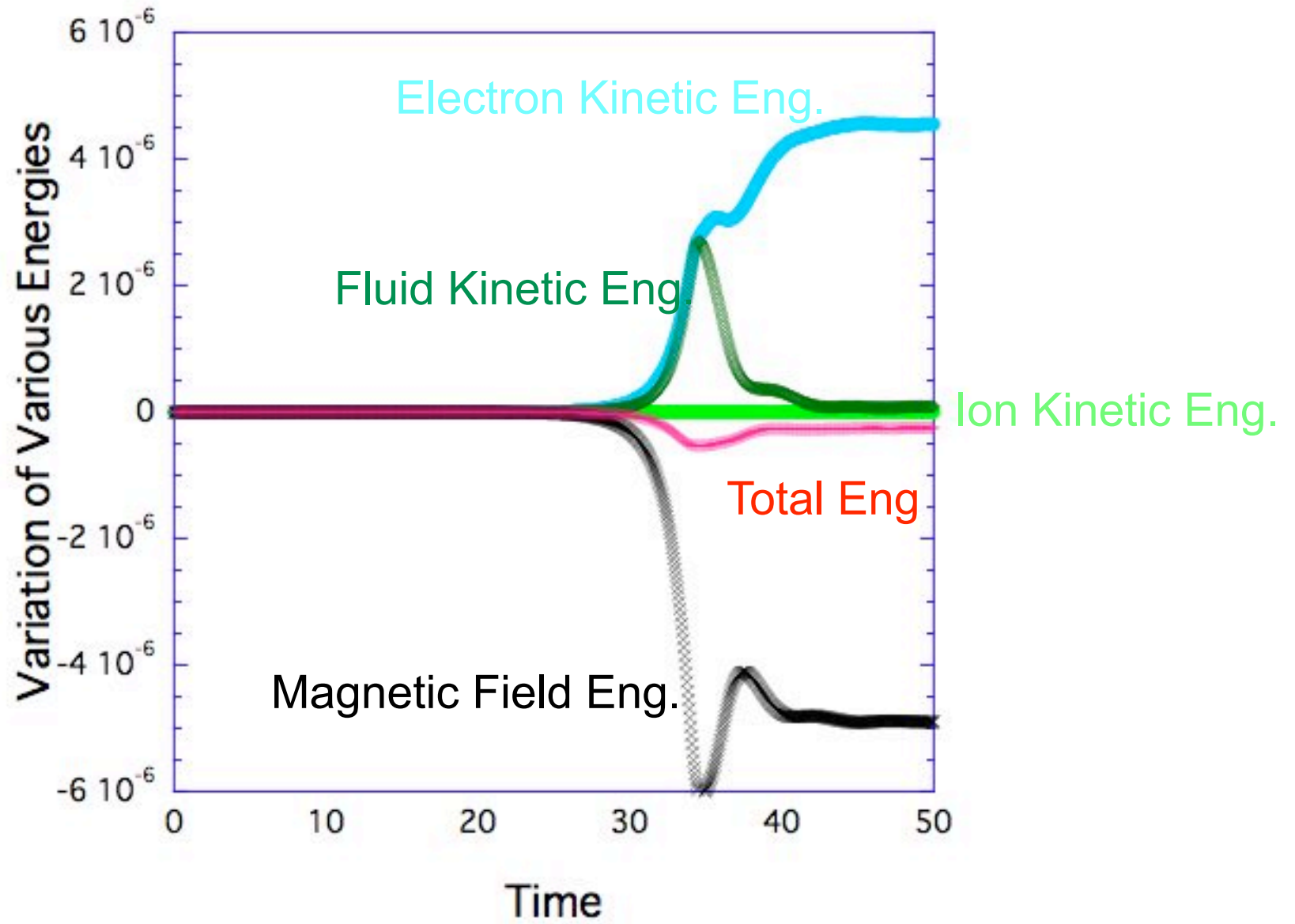
10000 steps

$$q(r) = q_0 \left[ 1 - 4 (1 - q_0) \left( \frac{r}{a} \right)^2 \right]^{-1}$$

$$q_0 = 0.85, \quad q(0.5a) = 1.0, \quad q_a = 2.125$$

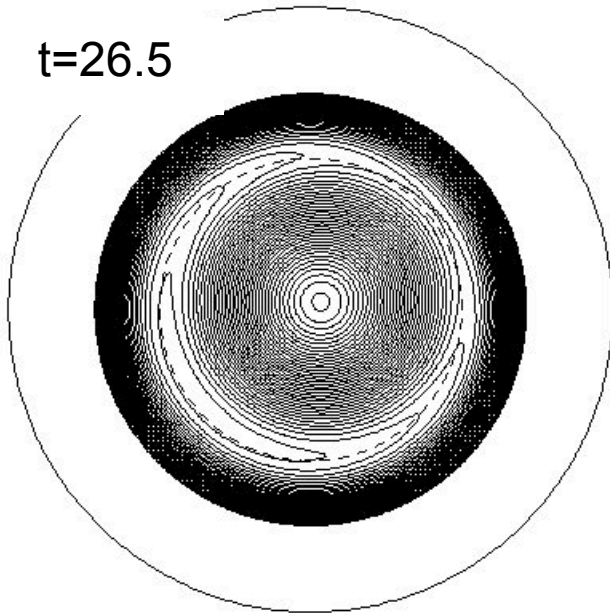
(0.5 million electrons + 0.5 million ions)  $\times$  number of CPU's

512 processors

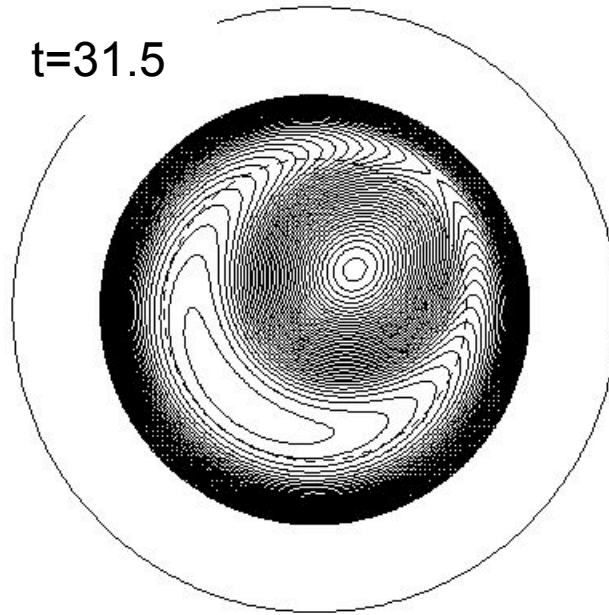


# Temporal Behavior of the Magnetic Field Structure

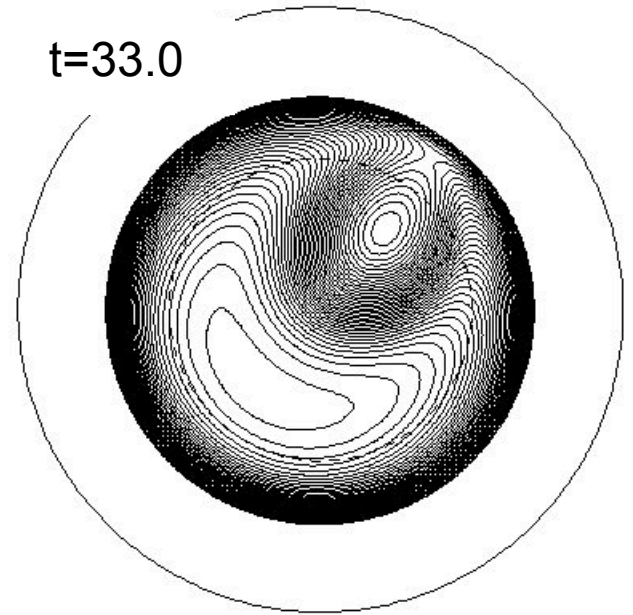
t=26.5



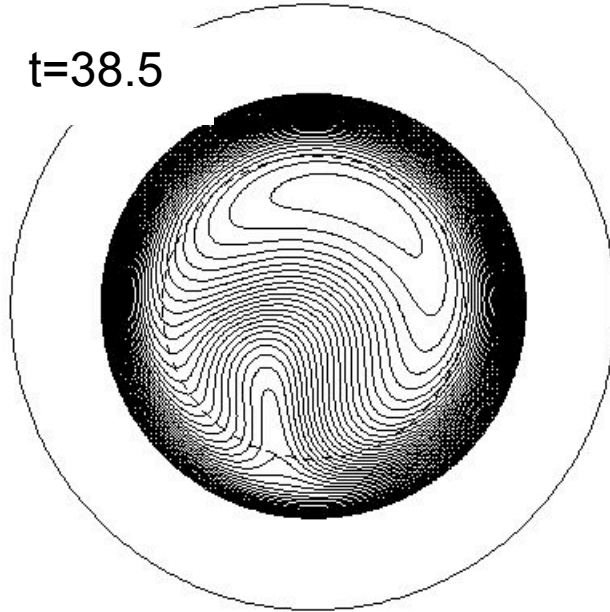
t=31.5



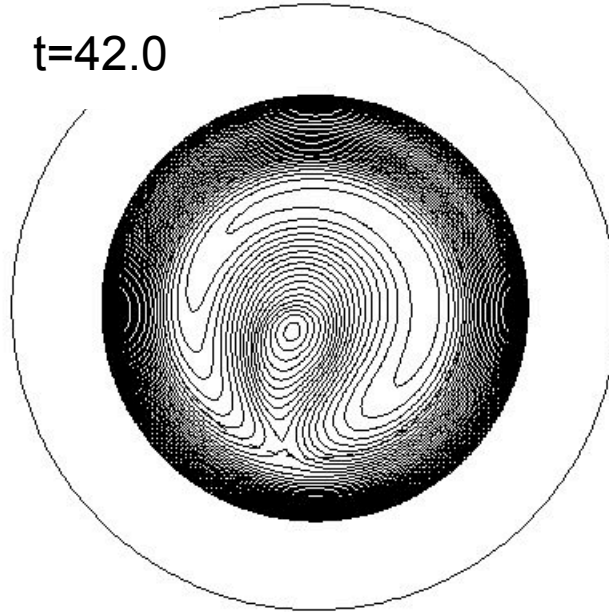
t=33.0



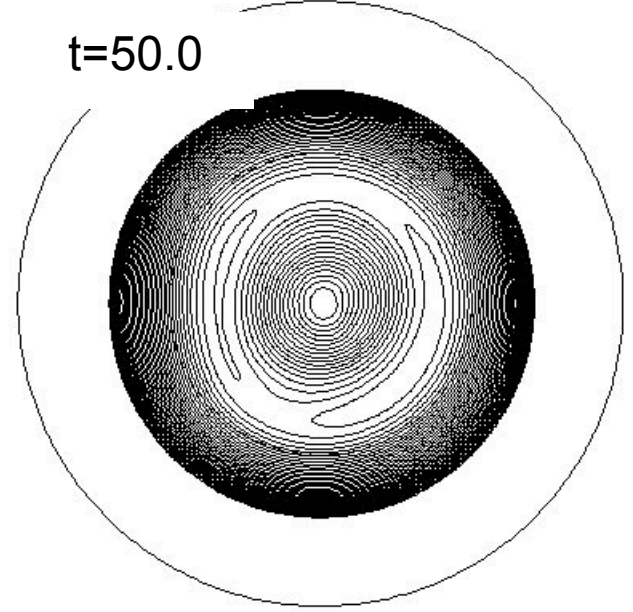
t=38.5



t=42.0

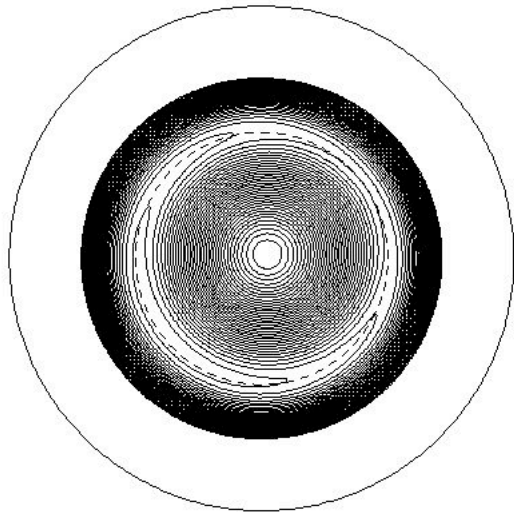


t=50.0

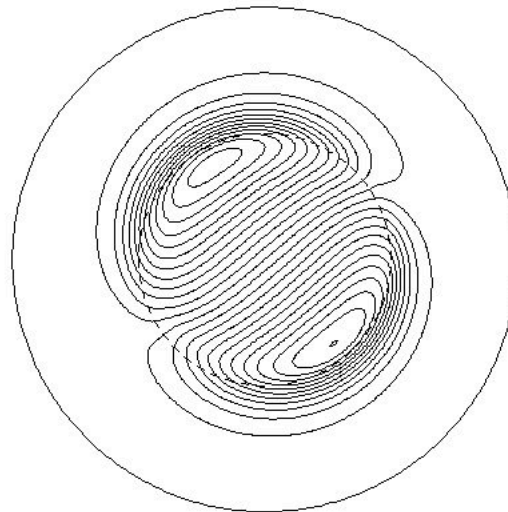


$t = 25$

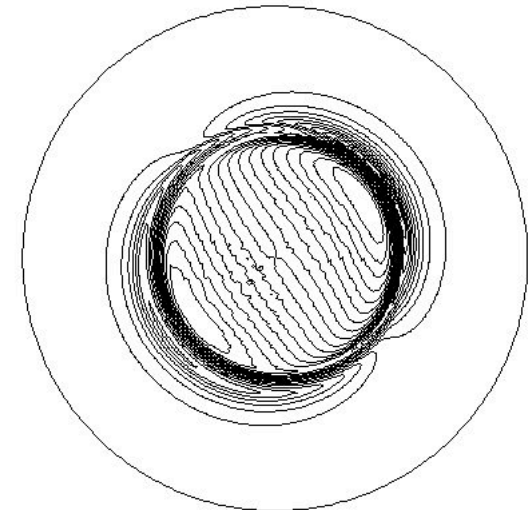
(a) Magnetic Field Structure

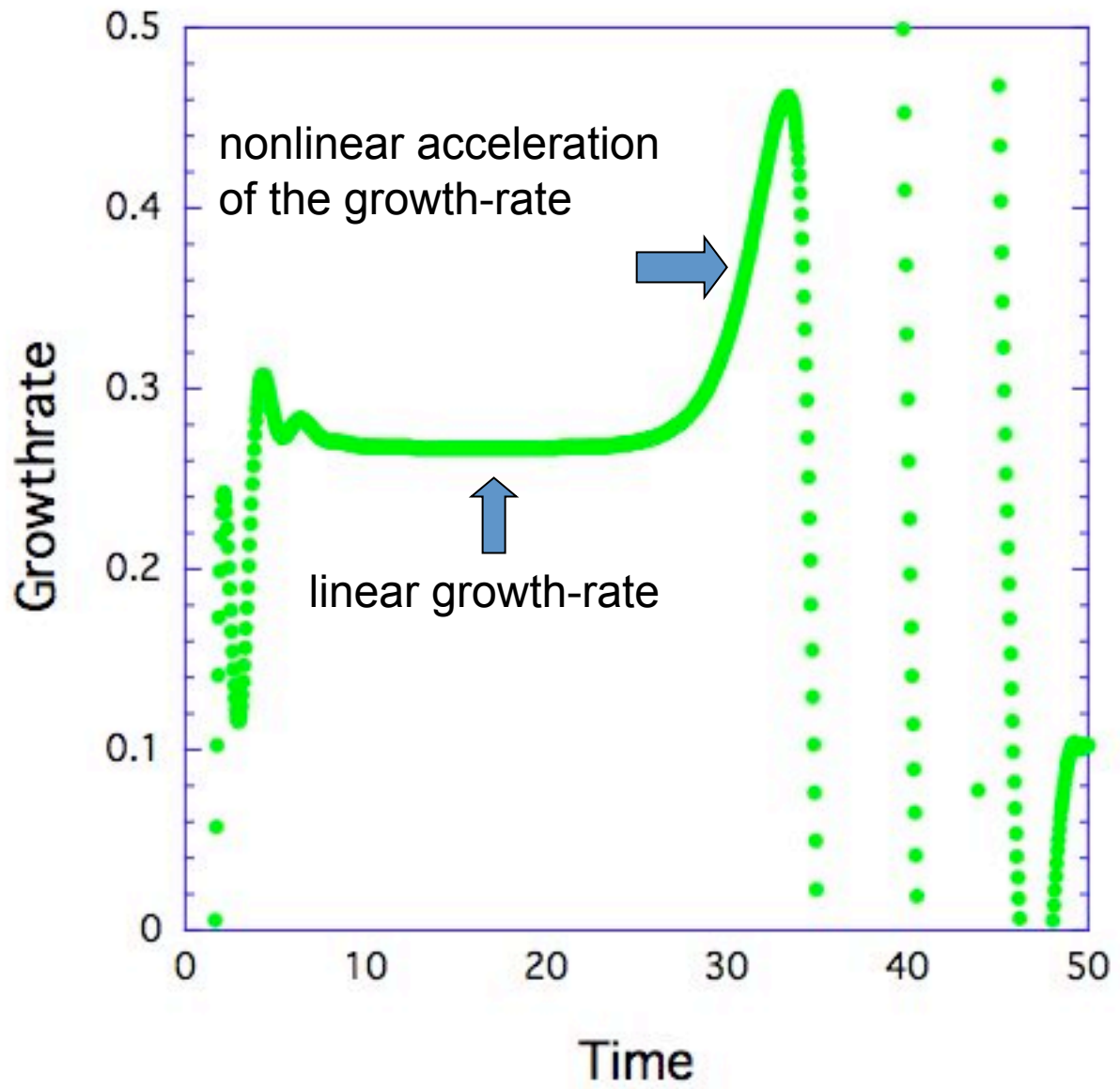


(b) Electrostatic Potential Profile



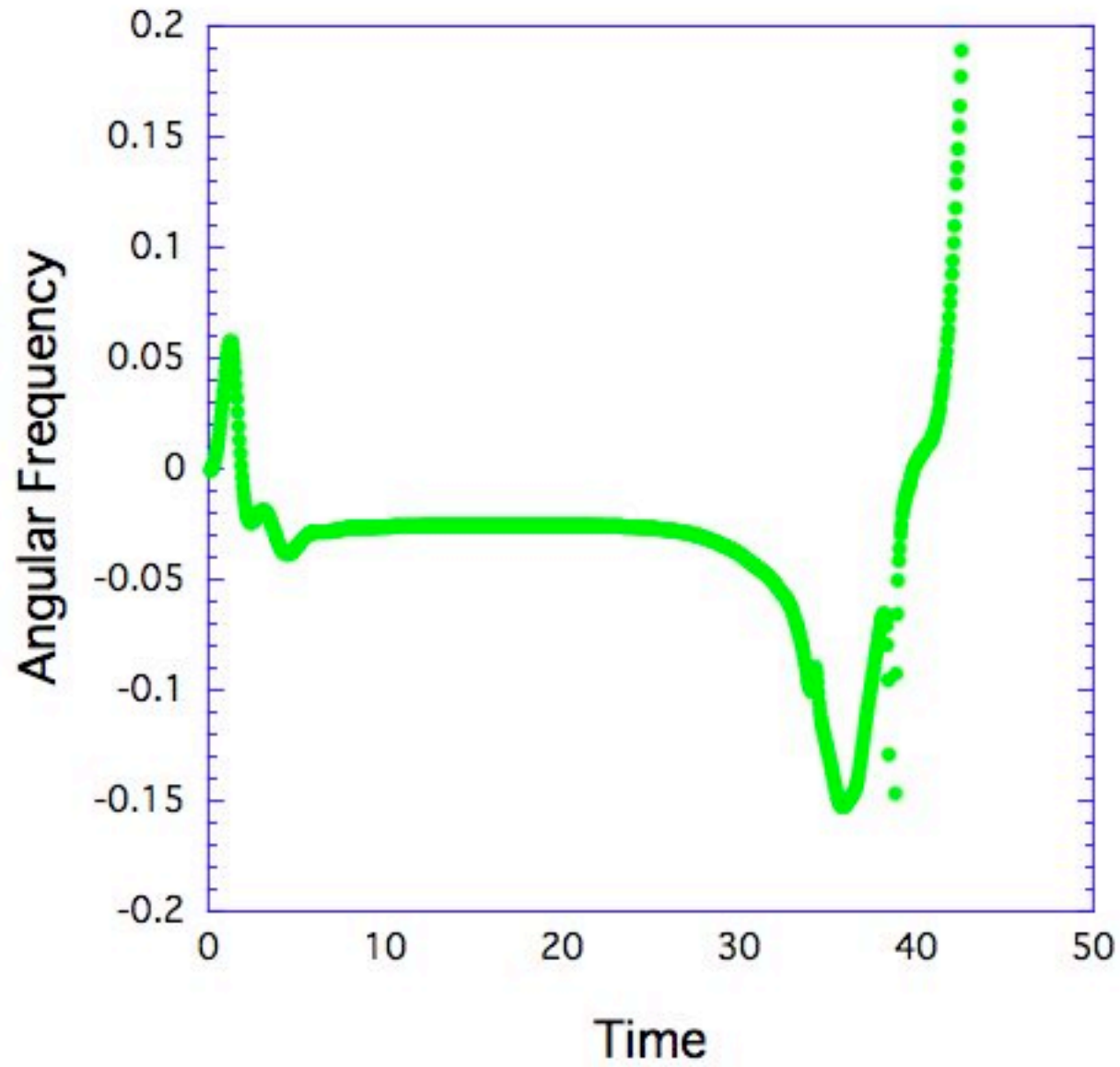
(c) Current Density Profile





GRM code  
 $\gamma = 0.318$

Plasma is slightly Rotating.  
Reason: ?



## 5. Performance on the parallel computer

1. Single-helicity version of Gpic-MHD  
2-dimensional code  
use replicas for field quantities
2. Multi-helicity version of Gpic-MHD  
3-dimensional code  
domain decomposition in  $z$  + replicas

-----  
Parallel computer

JAEA Altix3700Bx2

Intel Itanium2 (1.6GHz, 6.4Gflops)

NUMALink4

2048 cores (128 cores / node, 16 nodes)

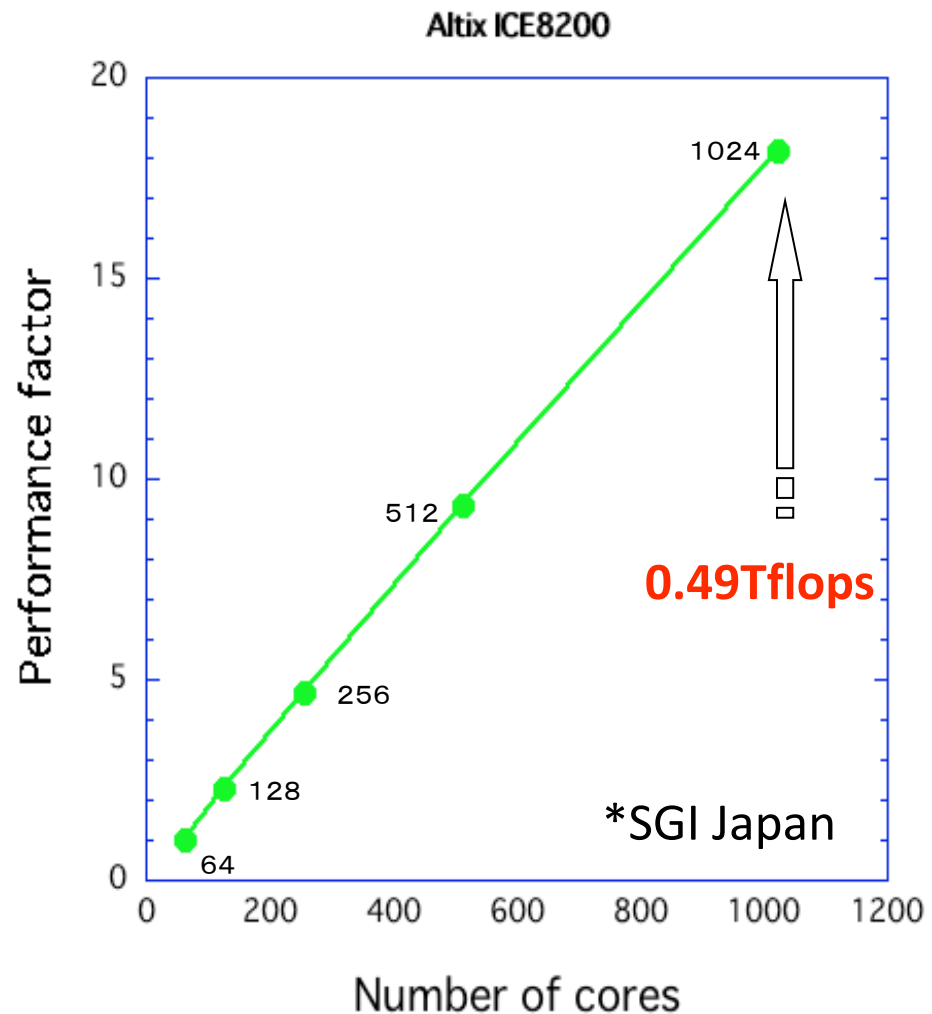
13.1 T-Flops

**1 million particles / core**

## Performance of Gpic-MHD on Altix ICE8200

Intel Xeon CPU X5365  
(3.0GHz, 12 Gflops)  
1024 cores  
4xDDR InfiniBand

- million particles / core
- 2000 steps
- 129x128x128 meshes
- 3D code with domain decomposition in z (64 segments) + replicas
- normalized by the case with 64 cores



## 6. Revisit the Formulation of Split-Weight Scheme

- $v_z$ -version
    - include electron thermodynamic response
    - lower noise
    - large time step size
  - $p_z$ -version
    - +
    - generalized potential
    - solve cancellation problem
- This version seems very complicated, but .....

# gyrokinetic Vlasov equation

$$p_z = v_z + \frac{q_s}{m_s} A_z$$

$v_z$  - version

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + \frac{d\mathbf{x}_s}{dt} \cdot \frac{\partial f_s}{\partial \mathbf{x}} + \frac{dv_{zs}}{dt} \frac{\partial f_s}{\partial v_z}$$

$p_z$  - version

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + \frac{d\mathbf{x}_s}{dt} \cdot \frac{\partial f_s}{\partial \mathbf{x}} + \frac{dp_{zs}}{dt} \frac{\partial f_s}{\partial p_z}$$

where

$$\frac{d\mathbf{x}_s}{dt} = -\frac{\nabla\phi \times \mathbf{b}}{B_0} + v_z \mathbf{b}^*$$

$$\frac{dv_{zs}}{dt} = -\frac{q_s}{m_s} \left( \mathbf{b}^* \cdot \nabla\phi + \frac{\partial A_z}{\partial t} \right)$$

$$\frac{dp_{zs}}{dt} = -\frac{q_s}{m_s} (\mathbf{b} \cdot \nabla\phi - v_z \mathbf{b} \cdot \nabla A_z)$$

and

$$\mathbf{b}^* = \mathbf{b} + \frac{\nabla A_z \times \mathbf{b}}{B_0}$$

# Choices of $f_0$

For simplicity, temporary neglect the thermodynamic response.

conventional  $\delta f$   
 $v_z$ -version

split-weight-scheme  
 $p_z$ -version

$$p_z = v_z - \frac{e}{m_e} A_z$$

conventional  $\delta f$   
 $p_z$ -version

decomposition in  $\delta f$  method

$$f = f_0 + \delta f$$

choices of equilibrium verocity distribution fufnction :  $f_0$

$$1. f_{0e}(v_z) = n_{0e} \sqrt{\frac{m_e}{2\pi T_e}} \exp\left(-\frac{m_e v_z^2}{2T_e}\right)$$

$$2. f_{0e}(p_z, \mathbf{x}, t) = n_{0e} \sqrt{\frac{m_e}{2\pi T_e}} \exp\left(-\frac{m_e (p_z + \frac{e}{m_e} A_z)^2}{2T_e}\right)$$

$$= n_{0e} \sqrt{\frac{m_e}{2\pi T_e}} \exp\left(-\frac{m_e p_z^2}{2T_e}\right) \exp\left(\frac{e}{T_e} \Psi\right)$$

$$\text{where } \Psi = -p_z A_z - \frac{e}{2m_e} A_z^2$$

$$3. f_{0e}(p_z) = n_{0e} \sqrt{\frac{m_e}{2\pi T_e}} \exp\left(-\frac{m_e p_z^2}{2T_e}\right)$$

$$\text{Usually, } \Psi = \phi - p_z A_z - \frac{e}{2m_e} A_z^2$$

# $p_z$ -version: split-weight scheme

lower order moments for electrons :

$$\int f_{0e} dp_z = n_{0e}$$

$$\int \left( p_z + \frac{e}{m_e} A_z \right) f_{0e} dp_z = 0$$

$$\int \left( p_z + \frac{e}{m_e} A_z \right)^2 f_{0e} dp_z = n_{0e} v_{te}^2$$

gyrokinetic Poisson's equation :

$$\frac{\omega_{pi}^2}{\omega_{ci}^2} \nabla_{\perp}^2 \phi = \frac{e}{\epsilon_0} \int \delta f_e dp_z - \frac{e}{\epsilon_0} \int \delta f_i dp_z$$

Ampere's law :

$$\nabla_{\perp}^2 A_z = \mu_0 e \int \left( p_z + \frac{e}{m_e} A_z \right) \delta f_e dp_z - \mu_0 e \int \left( p_z - \frac{e}{m_i} A_z \right) \delta f_i dp_z$$

where

$$\delta f = \delta h$$

# $p_z$ -version: conventional $\delta f$

lower order moments for electrons :

$$\int f_{0e} dp_z = n_{0e}$$

$$\int \left( p_z + \frac{e}{m_e} A_z \right) f_{0e} dp_z = \frac{e}{m_e} n_{0e} A_z$$

$$\int \left( p_z + \frac{e}{m_e} A_z \right)^2 f_{0e} dp_z = n_{0e} v_{te}^2 + \left( \frac{e}{m_e} \right)^2 A_z^2$$

gyrokinetic Poisson's equation :

$$\frac{\omega_{pi}^2}{\omega_{ci}^2} \nabla_{\perp}^2 \phi = \frac{e}{\epsilon_0} \int \delta f_e dp_z - \frac{e}{\epsilon_0} \int \delta f_i dp_z$$

Ampere's law :

$$\begin{aligned} \nabla_{\perp}^2 A_z &= \frac{n_{0e} \mu_0 e^2}{m_e} A_z + \mu_0 e \int \left( p_z + \frac{e}{m_e} A_z \right) \delta f_e dp_z \\ &\quad + \frac{n_{0i} \mu_0 e^2}{m_e} A_z - \mu_0 e \int \left( p_z - \frac{e}{m_i} A_z \right) \delta f_i dp_z \end{aligned}$$

$$\therefore \nabla_{\perp}^2 A_z - \left( \frac{\omega_{pe}^2}{c^2} + \frac{\omega_{pi}^2}{c^2} \right) A_z = \mu_0 e \int \left( p_z + \frac{e}{m_e} A_z \right) \delta f_e dp_z - \mu_0 e \int \left( p_z - \frac{e}{m_i} A_z \right) \delta f_i dp_z$$

Problem of cancellation

# $p_z$ -version with 0-th order current (1)

$v_{De}$  : electron drift velocity along B - field

0 - th order electron velocity distribution :

$$f_{0e}(p_z, \mathbf{x}, t) = n_{0e} \sqrt{\frac{m_e}{2\pi T_e}} \exp\left(-\frac{m_e(p_z + \frac{e}{m_e} A_z - v_{De})^2}{2T_e}\right)$$
$$= n_{0e} \sqrt{\frac{m_e}{2\pi T_e}} \exp\left(-\frac{m_e(p_z - v_{De})^2}{2T_e}\right) \exp\left(\frac{e}{T_e} \Psi_e\right)$$

where  $\Psi_e = -(p_z - v_{De})A_z - \frac{e}{2m_e} A_z^2$

0 - th order ion velocity distribution :

$$f_{0i}(p_z, \mathbf{x}, t) = n_{0i} \sqrt{\frac{m_e}{2\pi T_e}} \exp\left(-\frac{m_e(p_z + \frac{e}{m_e} A_z)^2}{2T_e}\right)$$
$$= n_{0i} \sqrt{\frac{m_i}{2\pi T_i}} \exp\left(-\frac{m_e p_z^2}{2T_i}\right) \exp\left(\frac{e}{T_e} \Psi_i\right)$$

where  $\Psi_i = -p_z A_z - \frac{e}{2m_e} A_z^2$

## $p_z$ -version with 0-th order current (2)

lower order moments for electrons :

$$\int f_{0e} dp_z = n_{0e}$$

$$\int \left( p_z + \frac{e}{m_e} A_z \right) f_{0e} dp_z = n_{0e} v_{De}$$

$$\int \left( p_z + \frac{e}{m_e} A_z \right)^2 f_{0e} dp_z = n_{0e} v_{te}^2 + n_{0e} v_{De}^2$$

gyrokinetic Poisson's equation :

$$\frac{\omega_{pi}^2}{\omega_{ci}^2} \nabla_{\perp}^2 \phi = \frac{e}{\epsilon_0} \int \delta f_e dp_z - \frac{e}{\epsilon_0} \int \delta f_i dp_z$$

Ampere's law :

$$\nabla_{\perp}^2 \delta A_z = \mu_0 e \int \left( p_z + \frac{e}{m_e} A_z \right) \delta f_e dp_z - \mu_0 e \int \left( p_z - \frac{e}{m_i} A_z \right) \delta f_i dp_z$$

where

$$\delta f = \delta h$$

$$\delta A_z = A_z - A_{z0}$$

$$\nabla_{\perp} A_{z0} = \mu_0 e v_{De}$$

# $p_z$ -version with 0-th order current (3)

Summary of  $\delta f$  method

$\delta f$  (= split - weight scheme):

$$f = f_0 + \delta f$$

$$\delta f = wf$$

$$\therefore \frac{1}{f} = \frac{1-w}{f_0}$$

gyrokinetic Vlasov equation :

$$\frac{df}{dt} = \frac{df_0}{dt} + w \frac{df}{dt} + \frac{dw}{dt} f = 0$$

$$\therefore \frac{dw}{dt} = -\frac{1}{f} \frac{df_0}{dt} = -(1-w) \frac{1}{f_0} \frac{df_0}{dt}$$

For marker particles,

$$\delta f = \sum w_j \delta(\mathbf{x} - \mathbf{x}_j) \delta(p - p_j)$$

$$\frac{dw_j}{dt} = -(1-w_j) \frac{1}{f_0} \frac{df_0}{dt} \Big|_{\mathbf{x}=\mathbf{x}_j, p=p_j}$$

# $p_z$ -version with 0-th order current (4)

equation for weights of electrons :

$$f_{0e}(p_z, \mathbf{x}, t) = n_{0e} \sqrt{\frac{m_e}{2\pi T_e}} \exp\left(-\frac{m_e(p_z + \frac{e}{m_e} A_z - v_{De})^2}{2T_e}\right)$$

$$\frac{df_{0e}}{dt} = \frac{\partial f_{0e}}{\partial t} + \frac{d\mathbf{x}_e}{dt} \cdot \frac{\partial f_{0e}}{\partial \mathbf{x}} + \frac{dp_{ze}}{dt} \frac{\partial f_{0e}}{\partial p_z}$$

$$\therefore \frac{1}{f_0} \frac{df_{0e}}{dt} = \frac{m_e}{T_e} \left(p_z + \frac{e}{m_e} A_z - v_{De}\right) \left[ \frac{e}{m_e} \frac{\partial A_z}{\partial t} + \frac{d\mathbf{x}_e}{dt} \cdot \left( -\frac{e}{m_e} \nabla A_z + \nabla v_{De} \right) - \frac{dp_{ze}}{dt} \right]$$

$$\frac{dw_{ej}}{dt} = -(1 - w_{ej}) \frac{m_e}{T_e} \left(p_{zej} + \frac{e}{m_e} A_z - v_{De}\right) \left[ \frac{e}{m_e} \frac{\partial A_z}{\partial t} + \frac{d\mathbf{x}_{ej}}{dt} \cdot \left( -\frac{e}{m_e} \nabla A_z + \nabla v_{De} \right) - \frac{dp_{zej}}{dt} \right]$$

equation for weights of ions :

$$\frac{dw_{ij}}{dt} = -(1 - w_{ij}) \frac{m_e}{T_e} \left(p_{zij} - \frac{e}{m_i} A_z\right) \left[ \frac{e}{m_i} \frac{\partial A_z}{\partial t} + \frac{d\mathbf{x}_{ij}}{dt} \cdot \frac{e}{m_i} \nabla A_z - \frac{dp_{zij}}{dt} \right]$$

# $p_z$ -version with 0-th order current (5)

Comparison with  $v_z$ -version (1):

equation for weights of electrons in  $v_z$  formulation :

$$f_{0e}(v_z, \mathbf{x}) = n_{0e} \sqrt{\frac{m_e}{2\pi T_e}} \exp\left(-\frac{m_e(v_z - v_{De})^2}{2T_e}\right)$$

$$\frac{df_{0e}}{dt} = \frac{d\mathbf{x}_e}{dt} \cdot \frac{\partial f_{0e}}{\partial \mathbf{x}} + \frac{dv_{ze}}{dt} \frac{\partial f_{0e}}{\partial v_z}$$

$$\begin{aligned} \therefore \frac{1}{f_0} \frac{df_{0e}}{dt} &= \frac{m_e}{T_e} (v_z - v_{De}) \left( \frac{d\mathbf{x}_e}{dt} \cdot \nabla_{v_{De}} - \frac{dv_{ze}}{dt} \right) \\ &= \frac{1}{f_0} \frac{df_{0e}}{dt} \Big|_{\text{pz-version}} \end{aligned}$$

$\therefore$  see next slide

# $p_z$ -version with 0-th order current (6)

Comparison with  $v_z$ -version (2):

$$\begin{aligned}
 \therefore & \quad \underline{-\frac{e}{m_e} \frac{\partial A_z}{\partial t} + \frac{d\mathbf{x}_e}{dt} \cdot \left( -\frac{e}{m_e} \nabla A_z + \nabla v_{De} \right) - \frac{dp_{ze}}{dt}} \\
 & = \frac{d\mathbf{x}_e}{dt} \cdot \nabla v_{De} - \frac{e}{m_e} \frac{\partial A_z}{\partial t} - \frac{e}{m_e} \left( -\frac{\nabla \phi \times \mathbf{b}}{B_0} + v_z \mathbf{b}^* \right) \cdot \nabla A_z - \frac{e}{m_e} (\mathbf{b} \cdot \nabla \phi - v_z \mathbf{b} \cdot \nabla A_z) \\
 & = \frac{d\mathbf{x}_e}{dt} \cdot \nabla v_{De} - \frac{e}{m_e} \left( \mathbf{b}^* \cdot \nabla \phi + \frac{\partial A_z}{\partial t} \right) \quad \underbrace{\hspace{10em}}_{\text{canceled out}} \\
 & = \underline{\frac{d\mathbf{x}_e}{dt} \cdot \nabla v_{De}} - \frac{dv_z}{dt}
 \end{aligned}$$

where

$$\mathbf{b}^* = \mathbf{b} + \frac{\nabla A_z \times \mathbf{b}}{B_0}$$

# $p_z$ -version with 0-th order current and $\phi$ (1)

decomposition in  $\delta f$  method

$$f = f_0 + \delta f$$

0 - th order electron velocity distribution :

$$f_{0e}(p_z, \mathbf{x}, t) = n_{0e} \sqrt{\frac{m_e}{2\pi T_e}} \exp\left(\frac{e\phi}{T_e} - \frac{m_e(p_z + \frac{e}{m_e} A_z - v_{De})^2}{2T_e}\right)$$

0 - th order ion velocity distribution :

$$f_{0i}(p_z, \mathbf{x}, t) = n_{0i} \sqrt{\frac{m_e}{2\pi T_e}} \exp\left(-\frac{m_e(p_z + \frac{e}{m_e} A_z)^2}{2T_e}\right)$$

## $p_z$ -version with 0-th order current and $\phi$ (2)

lower order moments for electrons :

$$\int f_{0e} dp_z = n_{0e} \exp(e\phi/T_e)$$

$$\int \left( p_z + \frac{e}{m_e} A_z \right) f_{0e} dp_z = n_{0e} v_{De} \exp(e\phi/T_e)$$

$$\int \left( p_z + \frac{e}{m_e} A_z \right)^2 f_{0e} dp_z = n_{0e} v_{te}^2 \exp(e\phi/T_e) + n_{0e} v_{De}^2 \exp(e\phi/T_e)$$

gyrokinetic Poisson's equation :

$$\frac{\omega_{pi}^2}{\omega_{ci}^2} \nabla_{\perp}^2 \phi = \frac{en_{0e}}{\epsilon_0} \left[ \exp(e\phi/T_e) - 1 \right] + \frac{e}{\epsilon_0} \int \delta f_e dp_z - \frac{e}{\epsilon_0} \int \delta f_i dp_z$$

Ampere's law :

$$\nabla_{\perp}^2 \delta A_z = \mu_0 en_{0e} v_{De} \left[ \exp(e\phi/T_e) - 1 \right] + \mu_0 e \int \left( p_z + \frac{e}{m_e} A_z \right) \delta f_e dp_z - \mu_0 e \int \left( p_z - \frac{e}{m_i} A_z \right) \delta f_i dp_z$$

where

$$\delta A_z = A_z - A_{z0}$$

$$\nabla_{\perp} A_{z0} = \mu_0 e v_{De}$$

# $p_z$ -version with 0-th order current and $\phi$ (3)

equation for weights of electrons :

$$\begin{aligned} \therefore \frac{dw_{ej}}{dt} &= -(1 - w_{ej}) \frac{1}{f_0} \frac{df_{0e}}{dt} \\ &= -(1 - w_{ej}) \left\{ \frac{e}{T_e} \left( \frac{\partial \phi}{\partial t} + v_z \mathbf{b}^* \cdot \nabla \phi \right) \right. \\ &\quad \left. + \frac{m_e}{T_e} \left( p_z + \frac{e}{m_e} A_z - v_{De} \right) \left[ -\frac{e}{m_e} \frac{\partial A_z}{\partial t} + \frac{d\mathbf{x}_e}{dt} \cdot \left( -\frac{e}{m_e} \nabla A_z + \nabla v_{De} \right) - \frac{dp_{ze}}{dt} \right] \right\}_{\mathbf{x}=\mathbf{x}_j, p=p_j} \end{aligned}$$

where we have used the following relation

$$\frac{d\phi}{dt} = \frac{\partial \phi}{\partial t} + \frac{d\mathbf{x}_e}{dt} \cdot \nabla \phi = \frac{\partial \phi}{\partial t} + \left( -\frac{\nabla \phi \times \mathbf{b}}{B_0} + v_z \mathbf{b}^* \right) \cdot \nabla \phi = \frac{\partial \phi}{\partial t} + v_z \mathbf{b}^* \cdot \nabla \phi$$

equation for weights of ions :

$$\frac{dw_{ij}}{dt} = -(1 - w_{ij}) \frac{m_e}{T_e} \left( p_z - \frac{e}{m_i} A_z \right) \left[ \frac{e}{m_i} \frac{\partial A_z}{\partial t} + \frac{d\mathbf{x}_i}{dt} \cdot \frac{e}{m_i} \nabla A_z - \frac{dp_{zi}}{dt} \right]_{\mathbf{x}=\mathbf{x}_j, p=p_j}$$

## Equations for $\partial\phi/\partial t$ and $\partial A_z/\partial t$ (1)

Taking partial time derivative of gyrokinetic Poisson's equation and Ampere's law, we have

$$\frac{\partial}{\partial t} \nabla_{\perp}^2 \phi = -v_A^2 \mathbf{b}^* \cdot \nabla (\nabla_{\perp}^2 A_z) - \frac{\mathbf{b} \times \nabla \phi}{B_0} \cdot \nabla (\nabla_{\perp}^2 \phi)$$

: vortex equation

$$\begin{aligned} \frac{\partial}{\partial t} \nabla_{\perp}^2 A_z &= \mu_0 e^2 \left( \frac{n_e}{m_e} + \frac{n_i}{m_i} \right) \left( \frac{\partial A_z}{\partial t} + \mathbf{b}^* \cdot \nabla \phi \right) - \frac{\mathbf{b} \times \nabla \phi}{B_0} \cdot \nabla (\nabla_{\perp}^2 A_z) \\ &\quad - \mu_0 e \mathbf{b}^* \cdot \nabla \int v^2 f_e dp + \mu_0 e \mathbf{b}^* \cdot \nabla \int v^2 f_i dp \end{aligned}$$

: Ohm's law along the magnetic field

## Equations for $\partial\phi/\partial t$ and $\partial A_z/\partial t$ (2)

$$\mu_0 e^2 \left( \frac{n_e}{m_e} + \frac{n_i}{m_i} \right) = \left( \frac{1}{d_e^2} + \frac{1}{d_i^2} \right) + \left( \frac{1}{d_e^2} \frac{\delta n_e}{n_{0e}} + \frac{1}{d_i^2} \frac{\delta n_i}{n_{0i}} \right)$$

$$\begin{aligned} \therefore \left[ \left( \frac{1}{d_e^2} + \frac{1}{d_i^2} \right) - \nabla_{\perp}^2 \right] \left( \frac{\partial}{\partial t} A_z \right) &= - \left( \frac{1}{d_e^2} \frac{\delta n_e}{n_{0e}} + \frac{1}{d_i^2} \frac{\delta n_i}{n_{0i}} \right) \left( \frac{\partial}{\partial t} A_z \right) \\ &\quad - \left( \frac{1}{d_e^2} \frac{n_e}{n_{0e}} + \frac{1}{d_i^2} \frac{n_i}{n_{0i}} \right) \mathbf{b}^* \cdot \nabla \phi \\ &\quad + \frac{\mathbf{b} \times \nabla \phi}{B_0} \cdot \nabla (\nabla_{\perp}^2 A_z) + \mu_0 e \mathbf{b}^* \cdot \nabla \int v^2 f_e dp - \mu_0 e \mathbf{b}^* \cdot \nabla \int v^2 f_i dp \end{aligned}$$

Assuming

$$m_e / m_i \ll 1, \quad \delta n_e \ll n_{e0}, \quad \delta n_i \ll n_{i0}$$

$$\int v^2 f_e dp = \frac{P_e}{m_e} = \frac{n_e T_{e0}}{m_e}, \quad \int v^2 f_i dp = \frac{P_i}{m_i} = \frac{n_i T_{i0}}{m_i}$$

we have the Ohm's law along the magnetic field in GRM.

$$\frac{\partial}{\partial t} A_z = -\mathbf{b}^* \cdot \nabla \phi + d_e^2 \frac{d}{dt} (\nabla_{\perp}^2 A_z) + \frac{T_{e0}}{n_{e0} e} \mathbf{b}^* \cdot \nabla n_e$$

# Moment integrals for $\delta f$

0 - th order moment :

$$\begin{aligned}\int \delta f_s dp_z &= \int \delta f_s dp_z \\ &= \sum w_{sj} \delta(\mathbf{x} - \mathbf{x}_{sj})\end{aligned}$$

1st order moment :

$$\begin{aligned}\int v_z \delta f_s dp_z &= \int \left( p_z - \frac{e_s}{m_s} A_z \right) \delta f_s dp_z \\ &= \sum p_{zsj} w_{sj} \delta(\mathbf{x} - \mathbf{x}_{sj}) - \frac{e_s}{m_s} A_z \sum w_{sj} \delta(\mathbf{x} - \mathbf{x}_{sj})\end{aligned}$$

2nd order moment :

$$\begin{aligned}\int v_z^2 \delta f_s dp_z &= \int \left( p_z - \frac{e_s}{m_s} A_z \right)^2 \delta f_s dp_z \\ &= \sum p_{zsj}^2 w_{sj} \delta(\mathbf{x} - \mathbf{x}_{sj}) - 2 \frac{e_s}{m_s} A_z \sum p_{zsj} w_{sj} \delta(\mathbf{x} - \mathbf{x}_{sj}) + \left( \frac{e_s}{m_s} \right)^2 A_z^2 \sum w_{sj} \delta(\mathbf{x} - \mathbf{x}_{sj})\end{aligned}$$

Alternative :

(1) Temporary calculate  $v_{sj}$  from  $p_{sj}$  and advance  $v_{sj}$  for a time step as well as  $p_{sj}$ .

(2) Use  $v_{sj}$  to estimate moment integrals.

(3) Calculate field quantities

(3) Go to (1) with  $t \rightarrow t + \Delta t$ .

**Important!!** With this alternative, we can calculate  $A_z$  directly by Ampere's law without iterations.

## 6. Summary

1. The **Gpic-MHD code** is developed in addition to the **GRM code**.
  - cylindrical geometry
  - non-uniform mesh in radial direction
  - use only standard techniques
  - single- and multi-helicity versions
2. Kinetic internal kink mode simulation was done successfully.
3. Comparison between Gpic-MHD and GRM is done.
4. Possible to do physically meaningful runs even on single PC or PC cluster.
5. Engineeringly meaningful runs need massive-parallel computer.
6. Performance on the Altix3700Bx2 parallel computer and Altix ICE8200 of SGI is investigated and no saturation is observed up to 1024 cores.
8. The formulation of split-weight scheme is revisited.
  - $p_z$  version and  $v_z$  version are the same mathematically
  - possibility of another advanced method

# Future Plan

1. Investigate scaling up to about 10000 cores.
2. Verify the numerically sound parameter range.
3. Inclusion of advanced techniques is ongoing.  
split-weight-scheme etc.
4. Toroidal version.

