Overfocusing in a Migma and Exyder Configurations

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September 1988
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Abstract

The theory of overfocusing is developed for a self-colliding storage ring (Exyder) and for a classical migma configuration. Forces due to external and self-generated equilibrium magnetic fields are considered. The band of energy containment is calculated for a model external magnetic field configuration. The forces due to self-generated magnetic fields in migma and Exyder can also cause overfocusing, and thereby set a beta limit on a migma disc and a luminosity limit on Exyder. The luminosity in Exyder can increase substantially if the self-colliding storage ring is partially unneutralized. The beta condition of a charge neutral thin migma limits the self-generated magnetic field to a fraction of the externally imposed magnetic field.

I. Introduction

In the migma concept [1] it is desired to store energetic ionized particles in an axial disc so that their orbits focus close to the axis of symmetry. This can be done with particles in a vacuum magnetic field that is similar to a mirror machine. These magnetic fields allow for orbit containment according to the principles used for confinement of plasmas in mirror machines or for confinement of accelerators with weak focusing fields. For the nearly ideal case, particles are almost monoenergetic, with an angular momentum distribution in $p_\theta$ peaked about $p_\theta = 0$ and the axial velocity, the velocity component parallel to the magnetic
field lines, much less than the velocity perpendicular to the magnetic field lines. The orbits have the pattern shown in Fig. 1, where all orbits pass very close to the origin, the radial extent of particle confinement region is two Larmor radii, and the spread in axial speed is so small that the axial extent of the migma, \( \Delta z \) is much less than the Larmor radius \( r_L \).

The energetic ions stored in migma establish "diamagnetic" currents that tend to cancel applied vacuum magnetic fields. In order to reduce the synchrotron radiation of a charge neutralizing electrons, a diamagnetic migma [2] has been proposed, in which the self-ion currents cancel the vacuum magnetic field in the bulk of the ion containment region.

Recently Blewett has suggested how a vacuum magnetic configuration can be designed so that magnetic fields are near zero throughout most of the ion storage region. His suggestion is the basis of Exyder, a proposal for a compact self-colliding storage ring [4].

In a proposed diamagnetic migma or Exyder, the absence of magnetic field in the bulk of the containment region means that magnetic focusing forces are most significant when an ion reaches the radial periphery of the containment region. At the radial periphery an ion feels a magnetic force that focuses its orbit radially and axially. The radial containment condition is straightforward; there needs to be enough magnetic flux to radially reflect the particle. The purpose of this paper is to discuss why axial focusing is a more subtle problem. There of course needs to be a net inward axial force. However, somewhat paradoxically, one can have a condition where there is too strong an inward axial force, which leads to axial expansion. We call such an effect "overfocusing."

In the Exyder configuration, ions move radially from the center, with negligible bending if the vacuum field is small, and turn around in the periphery where a magnetic field is high. Electric forces can be neglected when neutralizing low energy electrons are present that can be contained by an electric potential energy that is much less than the ion energy. A schematic of the orbits is shown in Fig. 2. Inside the dotted circle of radius \( R \), the magnetic field is considered negligible and ions move in straight lines. The magnetic field abruptly
rises to a mean value $B_0$ outside the dotted line (more discussion of this magnetic field is given in Sec. II). Outside $R$ the particles turn in a semicircular orbit, where the radius is approximately the Larmor radius, ($r_L$), and $r_L$ is small compared to $R$. In the Exyder proposal it is also assumed that the axial width, $\Delta z$, is small compared to $R$.

The focusing forces occur outside the radius $R$. The magnetic field is assumed to be strong enough to radially reflect the particle. The axial force felt by the particle is $F_z = \frac{q_0 B_r v_\theta}{c}$ ($q_0$ is the ion charge, $B_r$ the radial component of the magnetic field, $v_\theta$ the $\theta$-component of the velocity and $c$ the velocity of light). This force is felt during the relatively short time interval (compared to the time to move a distance $2R$) in which the particle is outside the radius $R$. Thus, in the time interval to radially turn around the particles receives an inward impulse per unit mass, given by

$$\Delta v = - \int \frac{dt q_i B_r v_\theta}{\gamma mc}$$

where $m$ is the ion mass and $\gamma = \frac{1}{\sqrt{1 - v^2/c^2}}$.

We shall show that if this inward impulse is too large, then the next time the particle returns to the focusing region at the opposite side of the $z$-midplane, it will have a larger amplitude. Orbit instability arises when this amplitude continues to increase with multiple passes. If we assume that the axial impulse received in the focusing region is proportional to $z$, i.e., $I_z = -z \Delta v / \Delta z$ with $I_z$ the axial impulse per unit relativistic mass, and $\Delta v$ the axial velocity increment received at $z = \Delta z$, then we derive from an impulse model that overfocusing arises, if

$$\frac{\Delta v T}{\Delta z} > 4,$$

where $T$ is the radial period of oscillation.

In this paper we describe in Sec. II how overfocusing can arise in a vacuum magnetic configuration which is relevant to the self-colliding storage rings concept. For a model magnetic field we determine the energy band of good containment. We then show in Sec. III how
diamagnetic effects in a standard migma configuration can also cause overfocusing. For a highly focused migma disc, the overfocusing criterion places a restriction on beta (the ratio of average kinetic energy density to magnetic field energy density in the region occupied by energetic particles) that can be achieved. The beta limit, $\beta_c$, is found to be given roughly by

$$\beta_c \approx \frac{2}{\ln(1/\epsilon)},$$

where $\epsilon = b/r_L$, with $r_L$ the ion particle Larmor radius, and $b = b_0 + \Delta z$, with $b_0$ the mean "impact parameter" which is the mean value of the distance of closest approach to the axis of symmetry, and $\Delta z$ the axial extent of the disc. The calculation also shows that the self-magnetic field of a thin axial disc-like migma configuration can produce only a fraction of the vacuum magnetic field. Thus, overfocusing by magnetic forces in a self-consistent equilibrium prevents the self-induced magnetic field from shielding in a substantial way the vacuum magnetic field. This means that a diamagnetic migma, where the magnetic field in the bulk of the containment region is much less than the magnetic field at the periphery, can not be achieved for a thin charge neutralized migma. In principle, in order to achieve a diamagnetic migma as described in Ref. 2, the axial width, $\Delta z$, has to be large compared to the ion containment radius.

It should also be noted that in the self-colliding storage ring, as the particle number increases, the self-consistent axial self-force can also violate the overfocusing condition and thereby set a limit to the total particle storage number; hence the luminosity of the stored particles' interaction rate. This limit is calculated in Sec. IV, and it is shown that the limiting luminosity of a large charge neutralized storage ring does not increase with radial size. The limiting luminosity, $L_c$, scales as $L_c \propto B_0 \gamma/m^2 \approx 3\Delta z/r_L \times 10^{40} \text{cm}^{-2}/\text{sec} \frac{B_0}{T}$ and $\gamma \approx 10$, where $B_0$ is the magnitude of the external magnetic field, $\gamma mc^2$ the energy of the ions with mass $m$, $\Delta z$ the axial extent of the disc and $r_L$ the Larmor radius in the magnetic field. However, a larger luminosity can in principle be obtained if one introduces compensating
defocusing forces. One obvious way is to control the charge imbalance of the energetic ions and background electrons. To take this possibility into account we have included in Sec. IV a model for self-generated electric fields arising from a lack of charge neutrality.

II. Overfocusing in Vacuum Magnetic Field

Let us consider an azimuthally symmetric magnetic field which is small and nearly constant at small radii, and changes rapidly in some interval around \( r \approx r_0 \), within a distance \( \Delta r \), as shown in Fig. 3. Such a field can be constructed by splitting two concentric solenoids as shown in Fig. 4. We shall use such a field for our modelling studies. The field is \( B_0 \) in the solenoidal shell, \( \lambda B_0 \), near the axis, and significant field variation exists near \( r = r_0 \) when \( z \lesssim \max(z_1, z_2) \).

In practice there are many variations of magnetic field coil designs to produce the fields of Fig. 3 at the \( z \) midplane. The ultimate choice should be made to economize on magnetic field energy and to optimize orbit stability [5]. However, for model studies we use magnetic fields that arise from the configuration shown in Fig. 4.

We only consider magnetic forces where kinetic energy does not change. Hence relativistic orbits can be evaluated from nonrelativistic theory if the relativistic mass is used instead of the rest mass. To consider orbits, we write the Hamiltonian per unit relativistic mass as

\[
2H = \frac{1}{r^2} (p_\theta - q\psi/(\gamma mc))^2 + v_z^2 + v_r^2,
\]

where \( H \) and \( p_\theta \) are the energy and angular momentum per unit relativistic mass, and \( v_r \) and \( v_z \) the axial and radial velocities. \( \psi(r, z) \) is the magnetic flux, and the magnetic field is given by

\[
B_z = \frac{1}{r} \frac{\partial \psi}{\partial r}, \quad B_r = -\frac{1}{r} \frac{\partial \psi}{\partial z}.
\]

To solve the orbits we assume \( p_\theta \approx 0 \) and the axial speeds \( v_z \) to be less than the perpendicular speeds \( v_\perp \approx (2H)^{1/2} \). Then we assume that in a single radial pass through the interaction
region around \( r \approx r_0 \), we can neglect the \( z \) motion and consider \( v_z \) constant. In this approximation, the time increment \( dt \) is

\[
dt = \frac{dr}{\left[2H - v_z^2 - (1/r^2) (p_\theta - q\psi(r, z)/(\gamma mc))^2\right]^{1/2}} = \frac{dr}{\left[2H - (1/r^2) (p_\theta - q\psi(r, z)/(\gamma mc))^2\right]^{1/2}}
\]

where \( z \) and \( v_z \) are fixed. The axial acceleration is

\[
a_z = -\frac{qv_\theta}{\gamma mc} B_r = -\frac{q}{\gamma mc} \left( p_\theta - \frac{q\psi(r, z)}{\gamma mc} \right) B_r,
\]

and the impulse per unit mass, \( \Delta v_z \), during a transit through the interaction region is

\[
\Delta v_z = -\int_{-T/2}^{T/2} dt \frac{q}{\gamma mc} v_\theta B_r
\]

\[
= \frac{2q}{\gamma mc} \int_{r_{\text{min}}}^{r} \frac{dr (p_\theta - q\psi(r, z)/(\gamma mc)) B_r}{r \left[2H - (1/r^2) (p_\theta - q\psi(r, z)/(\gamma mc))^2\right]^{1/2}}.
\]

where \( T \) is a radial bounce period, \( r_t \) and \( r_{\text{min}} \) are the outer radial turning point and inner turning point, respectively. Our expression is still valid if \( z \) varies appreciably in a radial bounce period, as long as \( z \) is nearly constant in the interaction region. Also note that the factor ‘2’ in the \( r \) integral arises from accounting for positive and negative radial velocities.

To simplify Eq. (2) further, we set \( p_\theta \) to zero, which is approximately valid if \( p_\theta \ll q\psi(r, 0)/\gamma mc \). Further, given \( B_z \), we can approximate \( B_r \), (using \( \nabla \times B = 0 \)):

\[
\frac{\partial B_x}{\partial z} = \frac{\partial B_z}{\partial r},
\]

which, upon integrating around the midplane, gives

\[
B_r = z \frac{\partial B_z(r, z = 0)}{\partial r}.
\]

Then using \( \psi = \int_0^r dr' B_z(r, z = 0) \) and approximating \( \psi \) about \( r = r_0 \),

\[
\Delta v_z = \frac{2q^2 z}{(\gamma mc)^2} \int_0^{r_{\text{e}}} \frac{dr (\partial B_z(r)/\partial r) \int_0^r dr' B_z(r')}{[2Hr^2 - (q/(\gamma mc)) \int_0^r dr' B_z(r')r'^2]^{1/2}}
\]
\[
\Delta v_z = \frac{2q^2 z r_0}{(\gamma mc)^2} \int_0^r \frac{dr (\partial B_z/\partial r) \left[ \int_0^r dr' \left( B_z(r') - B_z(0) \right) + r_0 B_z(0)/2 \right]}{\left\{ 2H r_0^2 - (q r_0/(\gamma mc))^2 \left[ \int_0^r dr' \left( B_z(r') - B_z(0) \right) + B_z(0)r_0/2 \right]^2 \right\}^{1/2}} \quad (3)
\]

Note that if the fields increase at small \( r \), the numerator is positive, and the contribution to \( \Delta v_z \) is positive, and therefore axially defocusing. At large radii \( \partial B_z/\partial r \) is negative, which contributes to axial focusing if the particle can reach this region. The stagnation that arises in the region where a particle turns radially tends to be strongly weighted because the denominator of Eq. (3) vanishes there. If this region is where \( \partial B_z/\partial r > 0 \), one tends to obtain a strong axial focusing contribution that overcomes the defocusing contribution from the smaller radii.

To cast the expression in a more dimensionless form, we define \( b(r) = B_z(r)/B_0 \), \( \omega_{c0} = qB_0/\gamma mc \), with \( B_0 \) the characteristic magnetic field at \( r \approx r_0 \), and \( r_L = (2H)^{1/2}/\omega_{c0} \equiv \) the Larmor radius of particle of energy \( H \) in uniform magnetic field \( B_0 \).

Then we find
\[
\frac{\Delta v_z}{\omega_{c0} r_0} = \frac{2z}{r_0} \int_0^r \frac{dr \partial b(r)}{dr} \left\{ \int_0^r dr' \left[ b_0(r') - b(0) \right] + (r_0/2)b(0) \right\} \left\{ r_L^2 - \left[ \int_0^r dr' \left( b(r) - b(0) \right) + (r_0b(0)/2) \right]^2 \right\}^{1/2} \quad (4)
\]
\[
\equiv -\frac{Iz}{r_0}
\]

This expression depends strongly on energy. The low energy particles are turned before they reach the region \( \partial B_z/\partial r < 0 \) and, hence \( I \) is intrinsically negative for such particles, and they cannot be contained axially. Higher energy particles have \( I \) positive, hence axial focusing properties. We also restrict \( r_L \) so that
\[
r_L < \max \left( \frac{1}{r} \int_0^r dr \ b(r) \right) \approx \frac{1}{r_0} \int_0^\infty dr \ rb(r),
\]
which guarantees radial focusing. This follows from the Hamiltonian when \( p_\theta = 0 \), as then
\[
v^2_r \leq 2H - \left( \frac{qv}{m\gamma cr} \right)^2 \equiv \omega_{c0}^2 \left[ r_L^2 - \frac{1}{r^2} \left( \int_0^r dr' rb(r) \right)^2 \right].
\]
As we assume $r_L < \max \left( \int_0^r dr b(r)r \right)$, there is a point $r_0$ where $r^2_L = \frac{1}{r_0^2} \int_0^{r_0} drr b(r)$. For small $r$, $\frac{1}{r^2} \left( \int_0^{r_0} drr b(r) \right) \approx \nu^2(0)/4$, hence $\nu^2 > 0$ for small $r$, and $\nu^2$ must vanish at a point $r = r_1 < r_0$. Thus, the radial containment region (the region where $\nu^2 > 0$) is limited to a radius less than $r_0$.

We now develop a mapping technique to study axial focusing if $I > 0$. Suppose a particle is at $z = z_n$ with an axial speed $v_z = v_n$ when it is about to enter the interaction region $r \approx r_0$. Upon passing through the interaction region it receives an impulse

$$\Delta v_z = -\omega_c I z_n,$$

so that its coordinates will be $z = z_n$ and $v_{n+1} = v_n - \omega_c I z_n$. If now a radial bounce period $T$ nearly elapses ($T \approx (4/\lambda \omega_c) \sin^{-1}(\lambda r_0/2r_L)$ and $\lambda B_0$ is the magnetic field at small radii), the particle will again be ready to enter the interaction region, and its coordinates are,

$$z_{n+1} = z_n + v_{n+1} T $$
$$v_{n+1} = v_n - \omega_c z_n I$$

(5)

The stability of this difference equation is found by seeking normal mode solutions $z_{n+1} = \Lambda z_n$, $v_{n+1} = \Lambda v_n$. Then solving Eq. (5) leads to the dispersion relation

$$\Lambda^2 - (2 - 4f) \Lambda + 1 = 0,$$

where $f = \Delta v_z T/4z_n = \omega_c T I/4$. The solutions for $\Lambda$ are

$$\Lambda = 1 - 2f \pm i2 \left( f - f^2 \right)^{1/2}.$$ 

Stability requires $|\lambda| > 1$, which restricts $f$ to the interval $0 < f < 1$. Satisfying the left side of the inequality is the condition for focusing. Satisfying the right-hand side of the inequality is the condition for avoiding "overfocusing."
In overfocusing, the impulse is so large that a particle achieves a larger amplitude in $|z_n|$ with each axial impulse, with the sign of $z_n$ alternating with each kick. It can be readily shown that for the critical case $f = 1$, a particle with a velocity $v_n = 2z_n/T$ and axial position $z = z_n$ receives an impulse $-4z_n/T$ and at its next interaction its coordinates are $v_{n+1} = -2z_n/T = -v_n$ and $z_{n+1} = -z_n$. It also follows that at $f = 1$ the particle passes through the origin when it passes through the axis. Any larger impulse will cause an exponential increase of the coordinates with successive interactions. These observations are consistent with a physical interpretation given by Blewett (private communication) for overfocusing. He considers a particle moving from the origin at a point 0 in Fig. 5. The particle moves in a straight line until it reaches the point $B$ at radius $R_0$. For $r > R_0$, the particle feels a strong focusing force causing the particle to reflect radially, and having its $v_z$ component changed. The particle returns to $r < R_0$ near the point $B$. The line $BC$ is the line of specular reflection. If the reflected trajectory returns on the dashed line, to the right of the line $BC$, we have a defocused system, while if the trajectory returns on the dotted line, to the left of $B$ we have an overfocused system.

It can also be shown that if a continuously applied focusing force is added to the impulsive focusing force considered here, the value of $f$ for which overfocusing occurs decreases. Hence, the external mirror fields makes the overfocusing condition slightly more restrictive. To counter overfocusing, one must compensate with defocusing forces.

It is also interesting to study Eq. (4) when $f$ is small, where the difference scheme can be converted to a differential equation. We have

$$\frac{dz}{dt} = \frac{z_{n+1} - z_n}{T} = v_z$$

$$\frac{dv_z}{dt} = \frac{v_{n+1} - v_n}{T} = \frac{4zf}{T^2}.$$  (6)
Combining these equations yields

$$\frac{d^2 z}{dt^2} + \frac{4f}{T^2} z = 0.$$  \hspace{1cm} (7)

Hence, the solution is

$$z = z_0 \cos(\omega_z t + \phi)$$

$$v_z = -\omega_z z_0 \sin(\omega_z t + \phi),$$  \hspace{1cm} (8)

with

$$\omega_z = \frac{2f^{1/2}}{T}.$$  

In practice, one may have a condition that particles must be stored within a distance $\Delta z$.

The axial spread in velocity then must satisfy

$$\frac{v_{z0}^2}{v_{10}^2} < \frac{\Delta z^2 \omega_z^2}{v_{10}^2} = \frac{\Delta z^2}{r_L^2} \frac{I}{\omega_0 T}$$  \hspace{1cm} (9)

$$\approx \begin{cases} \frac{\Delta z^2}{2\pi r_L^2} \frac{I}{r_0}, & \text{if} \quad \frac{\lambda R_0}{2r_L} \approx 1 \\ \frac{\Delta z^2}{2r_L r_0}, & \text{if} \quad \frac{\lambda R_0}{2r_L} \ll 1 \end{cases}.$$  

To illustrate the relevance of the orbit stability criteria, we consider the model field considered at the beginning of this section and illustrated in Fig. 4. Away from slots, the magnetic field in the sleeve is $B_0$ and the magnetic field in the central region is $\lambda B_0$.

Thus, the current density at $r = r_0 + \Delta x$ is $cB_0/4\pi$ while at $r = r_0 - \Delta x$ the current density is $cB_0(1 - \lambda)/4\pi$. We calculate the magnetic flux $\psi(r, z) = \int_0^r dr' r' B_z(r, z)$ in the vicinity of the slit assuming $2z_0 \approx 2x_0 \ll r_0$. The solution consists of the superposition of current densities

$$\mathbf{J} = \mathbf{J}_1 + \mathbf{J}_2$$

where

$$\mathbf{J}_1 = \frac{cB_0}{4\pi} \delta(r - r_0 - x_0) \hat{\theta} - \frac{(1 - \lambda)cB_0}{4\pi} \delta(r - r_0 + x_0) \hat{\theta}$$  \hspace{1cm} (10)
\[
\mathbf{J}_2 = -\frac{cB_0}{4\pi} \delta(r - r_0 - x_0)\theta(|z| - z_2)\hat{\theta} + \frac{(1 - \lambda)cB_0}{4\pi} \delta(r - r_0 + x_0)\theta(|z| - z_1)\hat{\theta}. \tag{11}
\]

The exact solution, as well as the approximate solution in the vicinity of \( r \approx r_0 \), for the magnetic flux function \( \psi_1 \) is (we define \( x = r - r_0 \)),

(a) \( r \leq r_0 - x_0 \)
\[ \psi_1(r, z) = \lambda B_0 \frac{r^2}{2} + \lambda B_0 r_0 x + \lambda \frac{B_0 r_0^2}{2} \]

(b) \( r_0 + x_0 < r < r_0 - x_0 \)
\[ \psi_1(r, z) = \lambda B_0 \frac{(r_0 - x_0)^2}{2} + \frac{B_0}{2} \left[r^2 - (r_0 - x_0)^2\right] \]
\[ \quad \div \quad \lambda \frac{B_0 r_0^2}{2} + B_0 r_0 (x + x_0) - \lambda B_0 r_0 x_0 \]

(c) \( r > r_0 + x_0 \).
\[ \psi_1(r, z) = B_0 \frac{(r_0 - x_0)^2}{2} + 2B_0 r_0 x_0 \]
\[ \quad \div \quad \lambda \frac{B_0 r_0^2}{2} + 2B_0 r_0 x_0 - \lambda B_0 r_0 x_0, \tag{12} \]

where in the approximate forms we have neglected term \( O(x_0^2) \).

For the currents \( \mathbf{J}_2 \), we neglect cylindrical effects for evaluating \( \psi_2 \) in the vicinity of \( r \approx r_0 \; |z| \approx z_1, z_2 \). Then treating the \( \mathbf{J}_2 \) current to be in a fixed direction we have

\[
\psi_2(r, z) \div -\frac{cr_0 B_0}{4\pi} \int_{-\infty}^{\infty} dy \left[ \int_{-z_2}^{z_2} \frac{dz'}{[(z - z')^2 + y^2 + (x - x_0)^2]^{1/2}} \right.
\]
\[
\left. - \int_{-z_1}^{z_1} \frac{dz'}{[(z - z')^2 + y^2 + (x + x_0)^2]^{1/2}} \right] \tag{13}.
\]

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These integrals can be performed straight-forwardly. For the integrals in Eq. (3) we then find

\[
\frac{1}{B_0} \int_0^r dr' r' B_z(r, 0) = \frac{1}{B_0} \left[ \psi_1(r, 0) + \psi_2(r, 0) \right] = r_0 \left\{ \frac{z_2}{2\pi} \ln \left[ \left( \frac{x}{x_0} - 1 \right)^2 + \frac{z_2^2}{x_0^2} \right] 
\right.
\left. - \frac{(1 - \lambda)z_1}{2\pi} \ln \left[ \left( \frac{x}{x_0} + 1 \right)^2 + \frac{z_1^2}{x_0^2} \right] 
\right. 
\left. + \frac{1}{\pi} (x - x_0) \tan^{-1} \left( \frac{z_2}{x - x_0} \right) - \frac{(1 - \lambda)}{\pi} (x - x_0) \tan^{-1} \left( \frac{z_2}{x - x_0} \right) \right\}
\right. 
\left. + \frac{\psi_1(r)}{B_0}, \right)
\]

with \(\psi_1(r)\) given in Eq. (12);

\[
\frac{1}{B_0} \frac{\partial B_z}{\partial r} = \frac{\partial B_r}{B_0 \partial z} = \frac{1}{B_0 r_0} \frac{\partial^2 \psi}{\partial z^2} = \frac{1}{\pi} \left[ \frac{z_2}{(x - x_0)^2 + z_2^2} - \frac{(1 - \lambda)z_1}{(x + x_0)^2 + z_1^2} \right].
\]

We substitute Eqs. (13) and (14) into Eq. (3) [or Eq. (4)] and evaluate the integral for \(I\) numerically. The relevant integral for orbit stability is \(f = \omega_0 TI/4\) so that stable orbits lie in the interval \(0 < f < 1\). \(f < 0\) is an unfocused orbit and \(f > 1\) is an overfocused orbit. The values of \(f\) as a function of \(r_L\) is given in Figs. (6a) and (6b). In Fig. (6a) \(z_1 = z_2\) and the various curves are for different values of \(z_1/x_0\). In Fig. (6b) we choose \(z_1 = x_0\) and the curves are for various \(z_2/z_1\). The most dramatic aspect of those curves is the steepness of curves as a function of \(r_L\). Roughly, these curves indicate that focused orbits occur in an energy interval \(\Delta E/E_0 \approx 10\%\) where \(\Delta E\) is the spread of energy about an energy \(E_0\) (where, say \(f = 1/2\)). This steepness in the energy dependence of \(f\) can be mitigated with careful magnetic field design as indicated by Blewett [5]. Nonetheless, the example shows that overfocusing is an important phenomena for orbit stability.
III. Overfocusing by Self-Magnetic Fields in Migma

We now show how overfocusing can arise in a self-consistent equilibrium, and we take a nearly ideal migma disc as an example. An ideal migma is a thin axial disc with axial length $\Delta z$ much less than the radius $r_0 = 2r_L$. All particles are nearly monoenergetic with a speed $v$ and have $p_\theta$ values close to zero. The equilibrium density, $n$ of an ideal migma is determined from the condition $nv_r = \text{constant}$ with $v_r = [2H - (q\psi/m\gamma_c^2)]^{1/2}$. In a nearly uniform magnetic field $B_0$, i.e. $2r_L(1/B)(\partial B_z/\partial r) \ll 1$, $n$ is then given by

$$n = \frac{2\bar{n}r_L\sigma(r)}{\pi r}, \quad (16)$$

with $\sigma(r) = (1 - r^2/4r_L^2)^{-1/2}$, where $r_L$ is the ion Larmor radius, $r_L = v/\omega_c$, and $\omega_c = \frac{qB_0}{\gamma mc}$. $\bar{n}$ is the mean density averaged over a cross-sectional area.

Notice that the density of an ideal migma is singular at the origin and at $r = 2r_L$. There are no particles for $r > 2r_L$. By considering a distribution function of finite width in $p_\theta$ and energy, these singularities are replaced by finite peaked function. Examples of such finite peaked functions can be found in Ref. 6, and a nonsingular form for $\sigma(r)$ can be used when there is a small spread. For example, given a distribution of particles with a characteristic of the impact parameter $b$ (i.e., $b$ is the characteristic distance of closest approach of a particle to the origin) one finds that

$$\frac{\sigma(r)}{r} \to \frac{1}{r(1 - r^2/4r_L^2)^{1/2}} \quad \text{if} \quad b \ll r \ll 2r_L - b$$

$$\frac{\sigma(r)}{r} \approx \frac{1}{b} \quad \text{if} \quad r \approx b$$

$$\frac{\sigma(r)}{r} \approx \frac{1}{r_Lb^{1/2}} \quad \text{if} \quad 2r_L - r \approx b$$

$$\frac{\sigma(r)}{r} \to 0 \quad \text{if} \quad r - 2r_L \gg b$$
The directed speed is \( v_\theta = -\omega_L z/2 \), so that the current density \( j_\theta \) is

\[
j_\theta = n q v_\theta = -\frac{\bar{n} q r_L \omega_L \sigma(r)}{\pi}.
\] (17)

Note that for an ideal migra, \( j_\theta \) is singular at \( r = 2r_L \). For a distribution function with a spread in \( p_\theta \) and energy, \( j_\theta \) is peaked but finite around \( r = 2r_L \).

For simplicity we take \( \bar{n} \) constant between \(-\Delta z/2 < z < \Delta z/2\). Our model can be further refined to allow \( \Delta z \) to be a function of \( r \), and we can even attempt to find an explicit distribution function whose density will replicate this property. However, the essential aspect of our model is that we have a thin disc of characteristic width \( \Delta z \ll r_L \), and \( \partial n/\partial z \) vanishes on the mid-plane. The induced magnetic fields produced inside the containment region of a general distribution will be quite similar to what is produced in the model we analyze.

The induced magnetic field, \( \mathbf{B}_1 \), is determined by the equations,

\[
\frac{\partial B_{1r}}{\partial z} - \frac{\partial B_{1z}}{\partial r} = \frac{4\pi}{c} j_\theta = -\frac{4\bar{n} q r_L \omega_L \sigma(r)}{c} \tag{18}
\]

\[
\nabla \cdot \mathbf{B}_1 \equiv \frac{\partial B_{1z}}{\partial z} + \frac{1}{r} \frac{\partial (r B_{1r})}{\partial r} = 0. \tag{19}
\]

As the axial variation is rapid, we can neglect \( (\partial B_{1z}/\partial r) \) in Eq. (18), so that \( B_r \) is found to be

\[
B_{1r} = \frac{4\bar{n} q r_L \omega_L \sigma(r)}{c} = -\frac{B_0 \bar{\beta} z \sigma(r)}{2\pi r_L}, \quad |z| < \frac{\Delta z}{2}, \tag{20}
\]

where \( \bar{\beta} = \gamma 8\pi \bar{n} m v^2 / B_0^2 \) is the mean beta, averaged over cross-sectional area of the particles in migra. We note that the evaluation of \( B_{1r} \) given Eq. (20) fails near the edge of an ideal migra when \( 2r_L - r \leq \Delta z \) as then \( \partial B_{1z}/\partial r \) cannot be neglected in Eq. (18) (as can be ascertained by calculating \( \frac{\partial B_{1z}}{\partial z} \approx \frac{B_{1z}}{\Delta z} \) in Eq. (19)). However, the expression for \( B_{1r} \) at \( r \approx 2r_L \) is valid if \( \Delta z < \sigma / (\partial g / \partial r) \), and this can be achieved if there is enough speed in say \( p_\theta \).

We note that \( B_{1r}/B_0 \approx \bar{\beta} z / r_L \), which needs to be small to justify neglecting self-fields in the equilibrium. Thus consistency requires \( \bar{\beta} \Delta z / r_L \ll 1 \). It can also be shown that
\( \frac{B_{1z}}{B_0} \approx \tilde{\beta} \Delta z \ln(\Delta z/r_L)/r_L \). Thus, with \( \tilde{\beta} \approx 1 \), we still have small self-field effects if \( \Delta z/r_L \ll 1 \).

The axial acceleration on a particle is

\[
a = \frac{F_z}{\gamma m} = -\frac{qv_\theta}{\gamma mc} B_{1r} = -\frac{\tilde{\beta} \omega_c^2 zr \sigma(r)}{4\pi r_L}, \tag{21}
\]

where we have used Eq. (20) and \( v_\theta = -\omega_c r/2 \). The axial impulse per unit relativistic mass this particle receives in passing through the outer radial periphery is, using Eq. (12),

\[
\Delta v = \int a \, dt = -\frac{\tilde{\beta} \omega_c^2}{4\pi r_L} \int dt \, zr \sigma(r). \tag{22}
\]

Let us assume \( z \) is nearly constant in passing through the outer periphery. Then,

\[
dt = \frac{dr}{v_r} \bigg|_{z = \text{const.}} = \frac{2dr}{\omega_c (4r_L^2 - r^2)^{1/2}}. \tag{23}
\]

Thus,

\[
\Delta v = \frac{-2\tilde{\beta} z \omega_c}{\pi} \int_{2r_L}^{r_L - \epsilon r_L} \frac{dr}{(4r_L^2 - r^2)^{1/2}} = \frac{-\tilde{\beta} \omega_c z \ln \left( \frac{1}{\epsilon} \right)}{\pi}, \tag{24}
\]

where \( dt \) is multiplied by a factor of two to take into account the positive and negative radial velocities. The cut-off \( \epsilon r_L \) is introduced in order to take account of the logarithmic singularity and \( r_L \gg 2r_L - r' \gg \epsilon \) the natural spread that exists in a nonideal migma. With the natural spreads, the expression for \( \Delta v \) is not divergent. By determining the limiting values where Eq. (24) is applicable, the magnitude of the large logarithmic response is found. Our calculation is only accurate to the extent \( \ln(1/\epsilon) \) is large. Two natural spreads determine the cut-off; \( \Delta r (\Delta r \approx \sigma(r)/\partial \sigma/\partial r \text{ at } r \approx 2r_L) \) and \( \Delta z \) with \( \epsilon r_L < \max(\Delta r, \Delta z) \). To logarithmic accuracy we can choose \( \epsilon r_L = \Delta r + \Delta z \) and incorporate both cases.

We have noted that when \( \Delta z > \Delta r \) our expression for \( B_{1r} \) fails when \( 2r_L - r \ll \Delta z \).

A proper evaluation of \( B_{1r} \) would lead to a contribution in Eq. (24) for \( r \approx 2r_L \) that is not divergent; the appropriate integration of this term would correct the logarithmic term proportional to \( \ln(1/\epsilon) \). We do not attempt to find this correction. If \( \Delta r > \Delta z \) the cut-off
parameter can be calculated relatively simply. In this case we note that \( B_{1r} \) can be obtained without any local breakdown of the expression and we have near \( r = 2r_L \),

\[
B_{1r} = z \frac{4\pi f^\circ}{c} \cdot -\frac{2\pi}{c} \omega_c r q n(r) z.
\]

We define a phase space mean of a physical quantity \( G(p_\theta, H, r) \) as

\[
\bar{G} = \frac{\int dp_\theta dh H F(p_\theta, H)}{\int dp_\theta dh H F(p_\theta, H)}.
\]

For highly peaked distributions all particles have nearly the same \( G \) value so that, \( \bar{G} \) characterizes the typical value of \( G \). Now let \( G \) be the impulse \( \Delta v \), so that the mean impulse \( \Delta v \) is

\[
\Delta v = -\frac{\int dp_\theta dh H F(p_\theta, H) \int dt q v_\theta B_{1r} / \gamma c n m}{\int dp_\theta dh H F(p_\theta, H)}
\]

\[
= -\frac{(2\pi q z \omega_c^3 / c B_0) \int dp_\theta dh H F(p_\theta, H) \int_{r_{min}}^{r_{max}} dr r^2 n(r) / v_r}{\int dp_\theta dh H F(p_\theta, H)}
\]

\[
= -\frac{2\pi q z \omega_c^3}{c B_0} \frac{\int_{r_{min}}^{r_{max}} dr r^2 n^2(r)}{\int dp_\theta dh H F(p_\theta, H)},
\]

(26)

where \( r_{min} \) should satisfy the condition

\[
1 \ll \frac{r_{min}}{\Delta r} \ll \frac{2r_L}{\Delta r} - 1.
\]

However, the logarithmic accuracy of the last term in Eq. (26) is not affected by replacing \( r_{min} \) by zero where we have used \( \int (dp_\theta dh / v_r) F(p_\theta, H) = r n(r) \). We note that \( \int_{r_{min}}^{r_{max}} dr r^2 n(r) \) is logarithmically large from the contribution near \( r \approx 2r_L \). For example, the following distribution function

\[
F(p_\theta H) = \frac{\bar{\beta} B_0^2}{4\pi^2 \gamma_m \omega_c} \delta \left( H - \frac{v_\theta^2}{2} \right) \theta \left( \frac{p_\theta^2}{v_\theta^2} - b_0^2 \right),
\]

characterizes a distribution function with a spread of impact parameters of width \( b_0 \), and the normalization constant is chosen to produce a sigma with a mean beta value, \( \bar{\beta} \) (if
$b_0 \ll r_L = v_0/\omega_c$. Here $\theta(x)$ is a step function. Using Eq. (26), the mean impulse on a particle is then found to be

$$\overline{\Delta v} = -\frac{2 \bar{\delta} \omega_c}{\pi} \int_0^{2+\epsilon} dx x^3 c^2(x, \epsilon)$$

where $c(x, \epsilon)$ is a normalized density which is a function of the radial coordinate $r = xr_L$ and the parameter $b_0 = \epsilon r_L$. Specifically, $c(x, \epsilon)$ is given by [6]

$$c(x, \epsilon) = \frac{1}{2x\epsilon} \int_{-\epsilon}^\epsilon d\epsilon' \left( \frac{4 - \frac{1}{x^2}(x^2 - 2\epsilon')^2}{\left[4 - \frac{1}{x^2}(x^2 - 2\epsilon)^2\right]^{1/2}} \right)$$

$$= \frac{1}{4\epsilon} \begin{cases} 
\pi, & 0 < x < \epsilon \\
\sin^{-1}\left[\frac{2+\epsilon}{2} \left( \frac{\epsilon}{x} - \frac{x}{2+\epsilon} \right)\right] + \sin^{-1}\left[\frac{(2-\epsilon)}{2} \left( \frac{x}{2} + \frac{\epsilon}{2-\epsilon} \right)\right], & \epsilon < x < 2 - \epsilon \\
\sin^{-1}\left[\frac{2+\epsilon}{2} \left( \frac{\epsilon}{x} - \frac{x}{2+\epsilon} \right)\right] + \frac{\pi}{2}, & 2 - \epsilon < x < 2 + \epsilon 
\end{cases}$$

To compare the result of a finite density profile with the ideal case, with cut-offs introduced as given by Eq. (24), we compare the function $Q_I(\epsilon) \equiv \frac{1}{2} \ln(1/\epsilon)$ with the integral $Q_s(\epsilon) \equiv \int_0^{2+\epsilon} dx x^3 c^2(x, \epsilon)$. We find $Q_I(0.01) = 3.45$, $Q_I(0.01) = 2.30$, $Q_I(0.1) = 1.15$ while $Q_s(0.001) = 4.55$, $Q_s(0.01) = 3.40$ and $Q_s(0.1) = 2.25$. Empirically, we find the difference $Q_s(\epsilon) - Q_I(\epsilon) = 1.1$, independent of $\epsilon$. Note that the numerical results gives a slightly larger $\overline{\Delta v}$ than the analytic estimate by an amount independent of $\epsilon$. Thus we see that the results obtained by taking into account finite radial spread, yields results compatible with our cut-off procedure.

We now determine the overfocusing condition using our analytic estimate. The radial bounce time is $T = 2\pi/\omega_c$. Thus, using $\Delta vT > 4z$, we find that the overfocusing instability arises in a disc-like migma when

$$\frac{\Delta v}{z} \left( \frac{2\pi}{\omega_c} \right) > 4$$

or
\[ \bar{\beta} > \frac{2}{\ln(1/\epsilon)}. \]  

(27)

The validity of this prediction requires

\[ \frac{\bar{\beta} \Delta z}{r_L} = \frac{2\epsilon'}{\ln(1/\epsilon)} < 1, \]  

(28)

where \( \epsilon' = \Delta z/r_L \).

The overfocusing condition then indicates that the disc must swell axially if \( \bar{\beta} \) is to be increased.

**IV. Overfocusing by Self-Magnetic Fields in Storage Rings**

The self-consistent overfocusing condition from magnetic fields in a nearly charge neutralized self-colliding storage charge neutralized ring configuration (Exyder) is now estimated. For simplicity we consider a system where particles are stored within a region \( r \lesssim r_0 \), where the magnetic field is negligibly small and the particles are turned around by a uniform vacuum magnetic field \( B_0 \), that is taken as constant for \( r > r_0 \). The turning radius in this magnetic field is \( r_L = v/\omega_c \) with \( \omega_c = qB_0/\gamma mc \). We assume \( r_L \ll r_0 \), and the focusing forces due to the vacuum magnetic fields is ignored. It can be shown that such focusing force causes a more restrictive overfocusing condition than we calculate. It is possible that a self-colliding system will not be totally neutralized. The space charge density is then \( gqn \), where \( g \) is the fraction of non-neutralization. If this non-neutral component can be controlled, we can compensate the magnetic overfocusing forces with defocusing electric forces, as will be illustrated.

The magnetic flux function for the configuration described is

\[ \psi = \begin{cases} 
0, & r < r_0 \\
\frac{1}{2}B_0(r^2 - r_0^2), & r > r_0 
\end{cases} \]  

(29)
The particle and current densities are taken constant in $z$ between $-\Delta z/2 < z < \Delta z/2$ and zero otherwise. The radial structure is given by,

$$n = \frac{\bar{n}v_{r_0}}{2r \left[ v^2 - (q\psi(r)/(\gamma mc\epsilon))^2 \right]^{1/2}},$$  \hspace{1cm} (30)$$

$$j_\theta = -\frac{\bar{n}v_{r_0}q^2\psi(r)}{2\gamma mc^2 \left[ v^2 - (q\psi(r)/(\gamma mc\epsilon))^2 \right]^{1/2}},$$  \hspace{1cm} (31)$$

where $\bar{n}$ is the average ion density in the disc, i.e. $\bar{n} \equiv N_T/(\pi r_0^2 \Delta z)$, where $N_T$ is the total number of particles stored. We have used the density and current of an ideally focused system. Using distribution functions the formulas can be modified (as in the previous section) to take into account peaked but finite spreads in phase space.

Substituting for $\psi$, we have

$$j_\theta = \begin{cases} 0, & r < r_0 \\ \frac{q\bar{n}v_{r_0}v_{\omega_c}(r^2 - r_0^2)}{4r^2 \left[ v^2 - \omega_c^2(r^2 - 2r_0^2 + r_0^4/r^2)/4 \right]^{1/2}}, & r_0 + r_L > r > r_0 \end{cases}$$  \hspace{1cm} (32)$$

Using $\partial B_r/\partial z = 4\pi j_\theta/c$ and $\partial E_z/\partial z = 4\pi n q g z$, we find for $-\Delta z/2 < z < \Delta z/2$,

$$B_r = \begin{cases} 0, & r < r_0 \\ -\frac{2\pi q\omega_c}{rc} n(r)(r^2 - r_0^2)z, & r_0 + r_L > r > r_0 \end{cases}$$  \hspace{1cm} (33)$$

$$E_z = 4\pi n(r)g(r)zq.$$  

The axial force per unit relativistic mass on a particle is

$$\frac{F_z}{\gamma m} = \frac{-q(v_\theta B_r/c - E_z)}{\gamma m} = \begin{cases} \frac{4\pi n(r)q^2g(r)z}{m\gamma}, & r < r_0 \\ -\frac{\pi q^2\omega_c^2}{\gamma mc^2} n(r)(r^2 - r_0^2)z + \frac{4\pi n(r)q^2g(r)z}{m\gamma}, & r_0 + r_L > r > r_0 \end{cases}$$  \hspace{1cm} (34)$$
If \( g(r = 0) = 0 \), we can use the impulse method developed in Sec. II for determining the overfocusing condition, as then the most significant axial forces occur near the outer particle turning point. If \( g(r = 0) \neq 0 \), the use of the impulse method is more complicated as particles can move an appreciable distance in \( z \) between impulses at \( r \approx r_0 + r_L \) and near \( r \approx b \). For simplicity, only the case where the impulse is only at the outer periphery will be studied.

The axial impulse, \( \Delta v \), is

\[
\Delta v = \int_{-T/2}^{T/2} \frac{F_z dt}{\gamma m}
\]

\[
= -\frac{2\pi q^2 z}{\gamma m} \int_{0}^{r_0 + r_L(1-\epsilon)} \frac{dr \left[ \omega_0^2 n(r)(r^2 - r_0^2)^2\theta(r - r_0) / r^2 c_0^2 - 4g(r)n(r) \right]}{r^3 \left[ v^2 - \omega_0^2 \theta(r - r_0)(r^2 - r_0^2)^2 / 4r^2 \right]^{1/2}}
\]

\[
= -\frac{\pi q^2 \bar{n} v r_0 z}{\gamma m} \int_{0}^{r_0 + r_L(1-\epsilon)} \frac{dr \left[ (r^2 - r_0^2)^2\theta(r - r_0)\omega_0^2 / c_0^2 - 4g(r)r^2 \right]}{r^3 \left[ v^2 - \omega_0^2 \theta(r - r_0)(r^2 - r_0^2)^2 / 4r^2 \right]} , \quad (35)
\]

where \( \theta(x) \) is a step function. These integrals have logarithmically divergent parts near \( r = r_0 + r_L \) and near \( r = 0 \). For \( r \approx r_0 \) we use \( r = r_0 + x \) and \( r^2 - r_0^2 \approx 2r_0 x \), and assuming \( x \ll r_0 \), we find

\[
\Delta v = -\frac{4\pi q^2 \bar{n} v r_L z}{\gamma m} \left[ \int_{0}^{r_L(1-\epsilon)} \frac{dx}{v^2 - \omega_0^2 x^2} \left( \frac{\omega_0^2 x^2}{c_0^2} - g_1 \right) \right]
\]

\[
= -\frac{2\pi q^2 \bar{n} v r_L z}{\gamma mc_0^2} \ln \left( \frac{1}{\epsilon} \right) \left[ 1 - \frac{c_0^2 g_1}{v^2} \right] = -\frac{\alpha \beta}{4} \omega_0 z \ln \left( \frac{1}{\epsilon} \right) , \quad (36)
\]

\( \alpha = 1 - g_1 c_0^2 / v^2, \epsilon = \Delta z / r_L + b / r_0, g_1 = g(r_0 + r_0 + r_L), b \) is the spread of the impact parameter and \( \beta = 8\pi \bar{n} m \gamma c_0^2 / B_0^2 \). The cut-off parameter is determined as follows. At \( r \approx r_0 + r_L \equiv r_1 \) there is an axial width \( \Delta z \). Our expression for \( B_r \) and \( E_z \) requires \( \Delta z \partial n / \partial r < n \), which restricts \( r_1 - r > \Delta z \). In addition, if there is a spread, at the impact parameter \( b \), the turning points near \( r = r_0 + r_L \) is smeared by a distance \( \approx b r_L / r_0 \). Thus the expression for the impulse near the outer periphery breaks down a distance \( \epsilon r_L \approx \Delta z + b r_L / r_0 \) from \( r_1 \). The
period of a radial bounce is \( T = 2r_0/v \), hence stability to overfocusing, \(|\Delta v/z|T < 4\), requires

\[
\bar{\beta} < \frac{r_L}{r_0 \ln(1/e)} \frac{8}{\alpha}.
\]

Equation (37) implies a limit on the luminosity of the Exyder storage ring. The luminosity is defined as

\[
L = c \int d^3r n^2
\]

\[
= \frac{2\pi c}{4\pi} \frac{\bar{\beta}B_0^2}{\bar{\beta}B_0^2} \Delta z \int_{r_0}^{r_L} \frac{d\bar{r}}{r}
\]

\[
= \frac{2\pi c}{4\pi} \frac{\bar{\beta}B_0^2}{\bar{\beta}B_0^2} \Delta z \ln\left(\frac{1}{\epsilon_1}\right) \bar{\beta}B_0^2 \frac{\Delta z \ln(1/\epsilon_1)}{\ln(1/\epsilon_1)} \left(\frac{2\pi c}{4\pi} \right)^2 \frac{\Delta z \ln(1/\epsilon_1)}{(8\pi)^2 m^2 \gamma^2 c^3},
\]

where \( \epsilon_1 = b/r_0 \), and we assume \( \gamma \gg 1 \). Thus, using Eq. (37), the luminosity is limited to

\[
L < \frac{B_0^2 r_L^2 \Delta z \ln(1/\epsilon_1)}{2\pi \ln(1/\epsilon_1) m^2 \gamma^2 c^3 \alpha^2} = \frac{\epsilon_2 \ln(1/\epsilon_1)}{\ln(1/\epsilon_1)} \frac{\gamma B_0^4}{2\pi \omega_{cr}^3 m^2 \alpha^2},
\]

where \( \epsilon_2 = \Delta z/r_L \) and \( \omega_{cr} = (qB/mc) \). As an example, consider \( B_0 = 5 \times 10^4 \) gauss, \( \gamma = 10 \), and \( m = \) protons. We find

\[
L < \frac{3.1 \times 10^4 \epsilon_2 \ln(1/\epsilon_1) \text{ cm}^{-2}}{\ln(1/\epsilon_1) \text{ sec}}.
\]

Note that for a charged neutral self-collider, the overfocusing condition limits the luminosity from scaling with radial size. However, a significant increase in luminosity can be achieved if \( \alpha \) can be made less than unity. Care with charge neutralization is needed, however, since \( \alpha < 0 \) causes defocusing.
References


5. J.P. Blewett (to be published).

Figure Captions

1. Schematic diagram of a thin migma. The ion orbits are nearly circular in shape and for flow in the direction of the arrows the circular shape precesses in the clockwise direction. Peak currents develop at the plasma edge at $r \approx 2r_L$ in the clockwise direction, where $r_L$ is the ion Larmor radius. The thickness $\Delta z$ of this migma is assumed small compared to $r_L$.

2. Exyder Configuration

Schematic orbits in the Exyder configuration. In the low magnetic field $r < r_0$ region, ions move radially with little bending. At $r > r_0$, the large magnetic field bends the ions in an approximate semicircular orbit of radius $r_L$ (the Larmor radius). Currents develop for $r > r_0$, and peak at $r \approx r_0 + r_L$. In this work the thickness $\Delta z$ is assumed small compared to $r_L$.

5. Focusing, defocus and overfocusing trajectories.

If point 0 is the origin of a "lens" with reflection symmetry, then a trajectory emerging from 0 is a focusing one, if on reflection at $B$, it lies within the angle $0BC$; the trajectory is a defocusing one if on reflection at $B$ it lies to the right of $BC$ (as the dashed line); the trajectory is an overfocusing one if on reflection at $B$ it lies to the left of $0B$ (to dotted line).